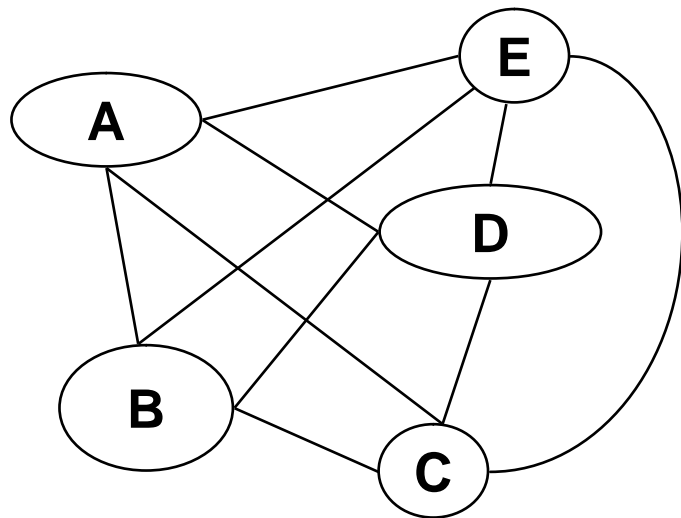


# Homework

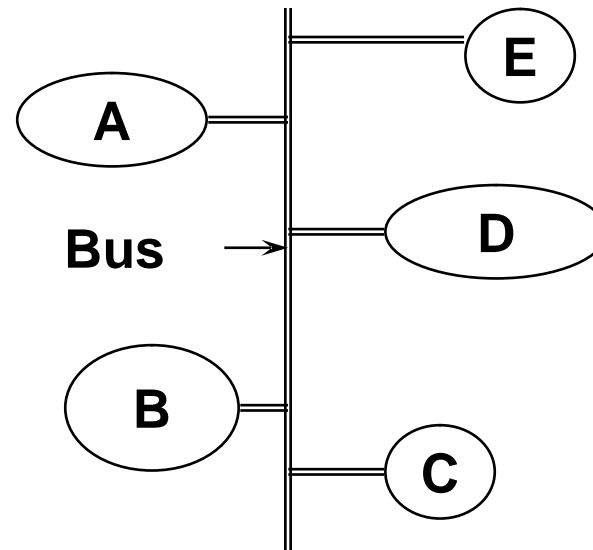
- Reading
  - Tokheim, Section 13-5 (Three State Buffers only)
- Machine Projects
  - Continue on MP5
- Labs
  - Continue labs with your assigned section

# Buses

- Concept is to link together multiple functional units over a common data highway at a lower cost than using multiple point to point links

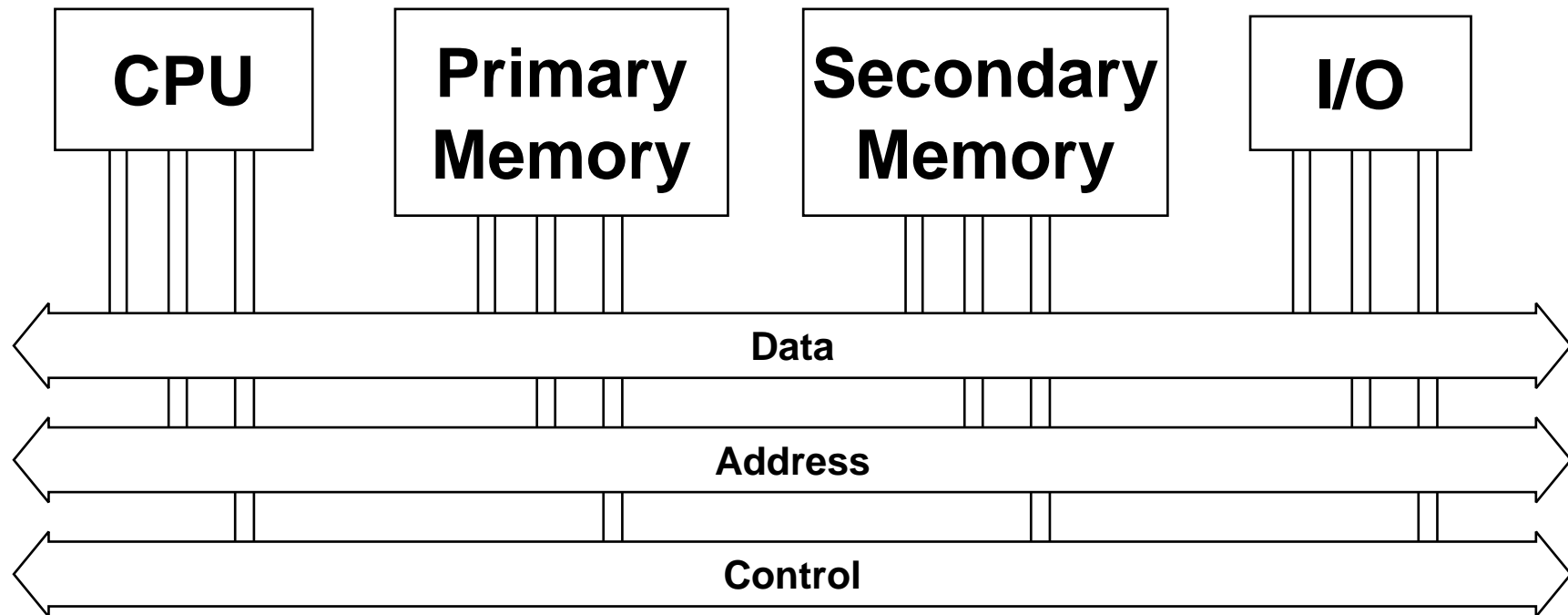


**OR**



$$\text{Number of Links} = n * (n - 1) / 2$$

# Bus - Essential Part of Any Computer

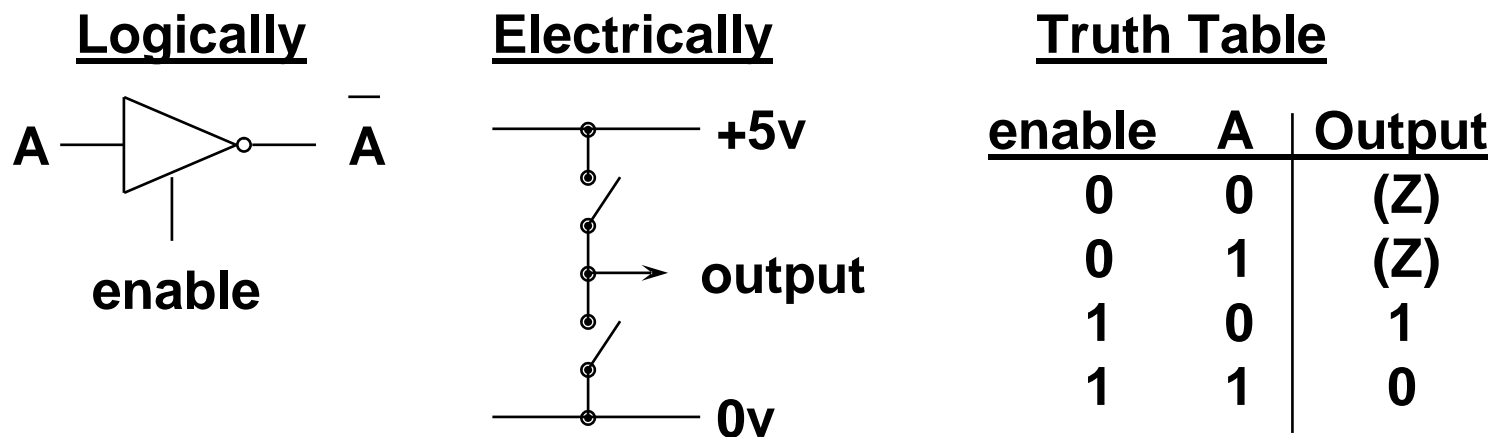


# Tri-state Logic Outputs

- Since we can have multiple masters on a bus, we need Tri-state logic for attachment to a bus so that each device can choose to drive or not drive the bus depending on whether it is the bus master for a given bus cycle
- Tri-state logic prevents a bus conflict where one device is driving a signal to 1 and another device is driving it to 0 at the same time - generates high current through wires (and smoke?)

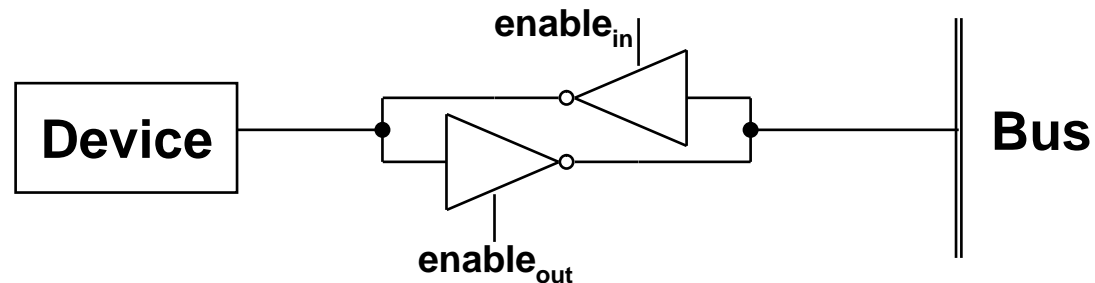
# Tri-State Logic

- The problem with connecting multiple “normal” outputs together on a bus is that each has to be in one logic state (0) or the other (1) - driving voltage on each bus signal high or low
- This represents a conflict over the state of the signal
- We resolve this conflict with tri-state logic

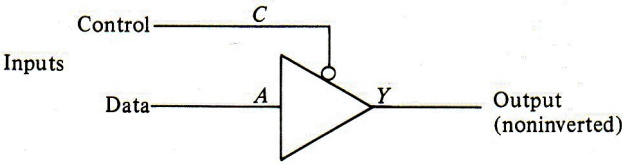


# Tri-State Logic and Buses

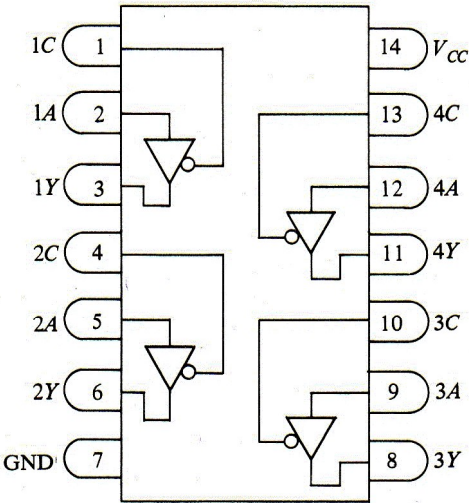
- The logical element has output enable pin to go from a floating output to drive the output from the circuit
- Inverters and buffers are used as bus drivers or buffers
  - Two such drivers or buffers in opposite directions are used to make the connection bi-directional
  - The gates also provide more “drive” onto the bus so that the bus signals are stronger and the bus can be longer



# Tri-State Logic and Buses



(a) Logic symbol of a three-state buffer



(b) Pin diagram

Inputs		Output
C	A	Y
L	L	L
L	H	H
H	X	(Z)

L = LOW voltage level  
H = HIGH voltage level  
X = don't care  
(Z) = high impedance (off)

(c) Truth table

Fig. 13-12 74125 quad three-state buffer IC

# Bus Master – Slave Relationships

- During any specific bus cycle, only one device attached to the bus is allowed to drive it
- Driving the bus means that a device is forcing each signal on the bus to a high or low state
- For the data bus, the processor, a memory chip, or an I/O device may be driving the data bus during a specific read or write bus cycle
- Specific signals on the address and control bus select a device to be the master on the data bus



# Bus Master – Slave Relationships

- Up till now, I have said that the address bus and the control bus are always driven by the processor, however that is NOT really true!
- That was only a “lie of simplification”!
- The processor is NOT the only device that may be driving the address and control busses
- Hopefully you are now well-prepared for me to un-simplify a bit J

# Bus Arbitration

- Bus arbitration is used to hand off a bus between one of several potential bus masters using signals that are a part of the bus itself
- A bus arbitration protocol implements some form of bus request and bus grant handshake to determine which device will be the master on the bus for the next bus cycle

# Bus Master – Slave Relationships

- Other devices that potentially can be the master on the address and control bus are:
  - Direct Memory Access (DMA) Controller
  - DRAM controller to refresh the stored bits
  - Other processors in multiprocessor architectures
- We'll only discuss the first application above, but not at the level of programming for it in detail – too hard to un-simplify that

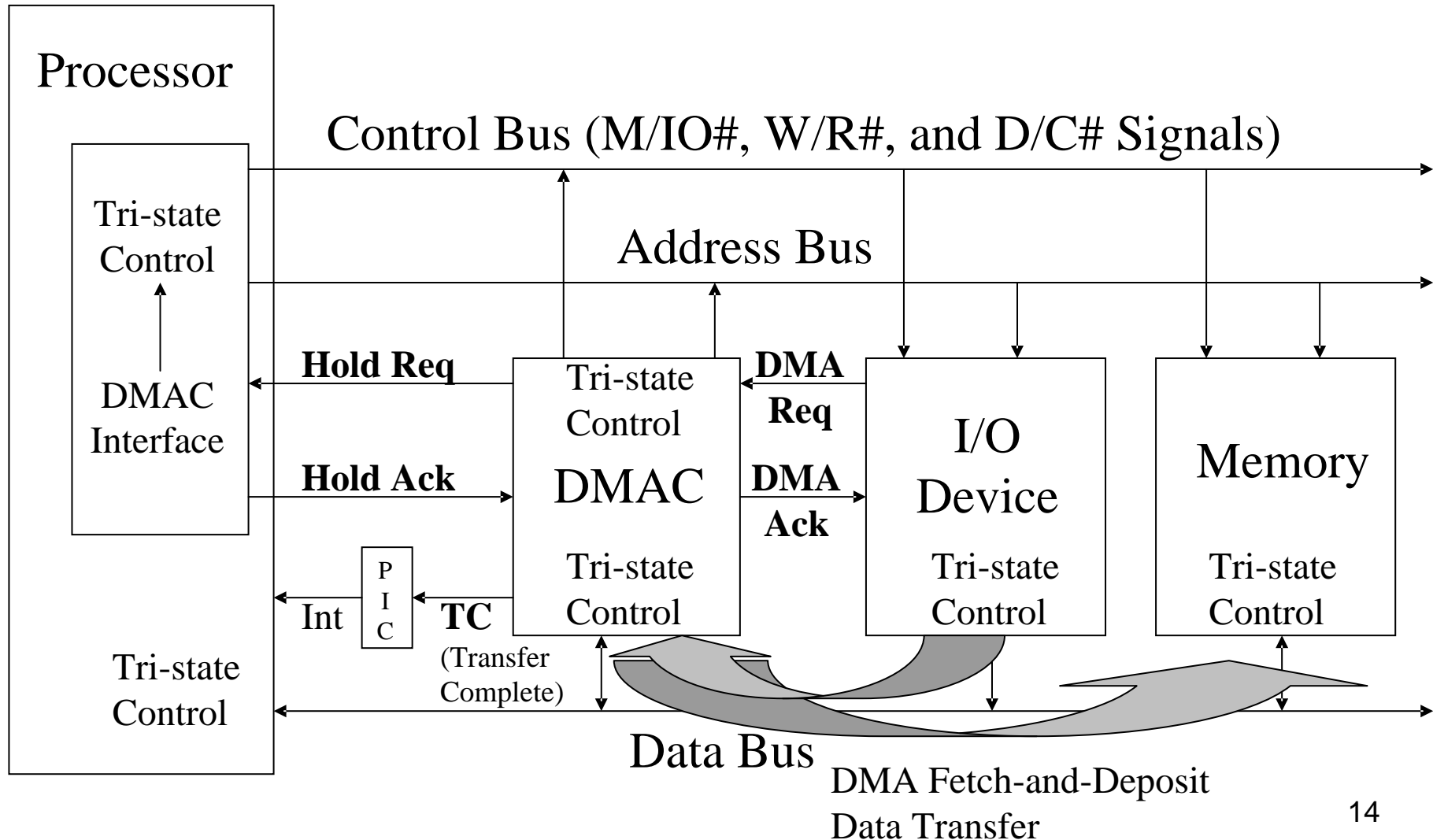
# Direct Memory Access

- You thought that handling an I/O device under interrupt control was pretty good – right?
- Wrong!
- The overhead to process an interrupt for each byte of data is still relatively costly in terms of processor time
  - Process interrupt and stack context of processor
  - Fetch and execute instructions of ISR
  - Move data from I/O device or memory to processor register
  - Move data from processor register to memory or I/O device
  - Restore context of processor and resume background code
- It is better if an I/O device like a disk can transfer data directly to or from the memory without the processor needing to execute any in or out instructions!

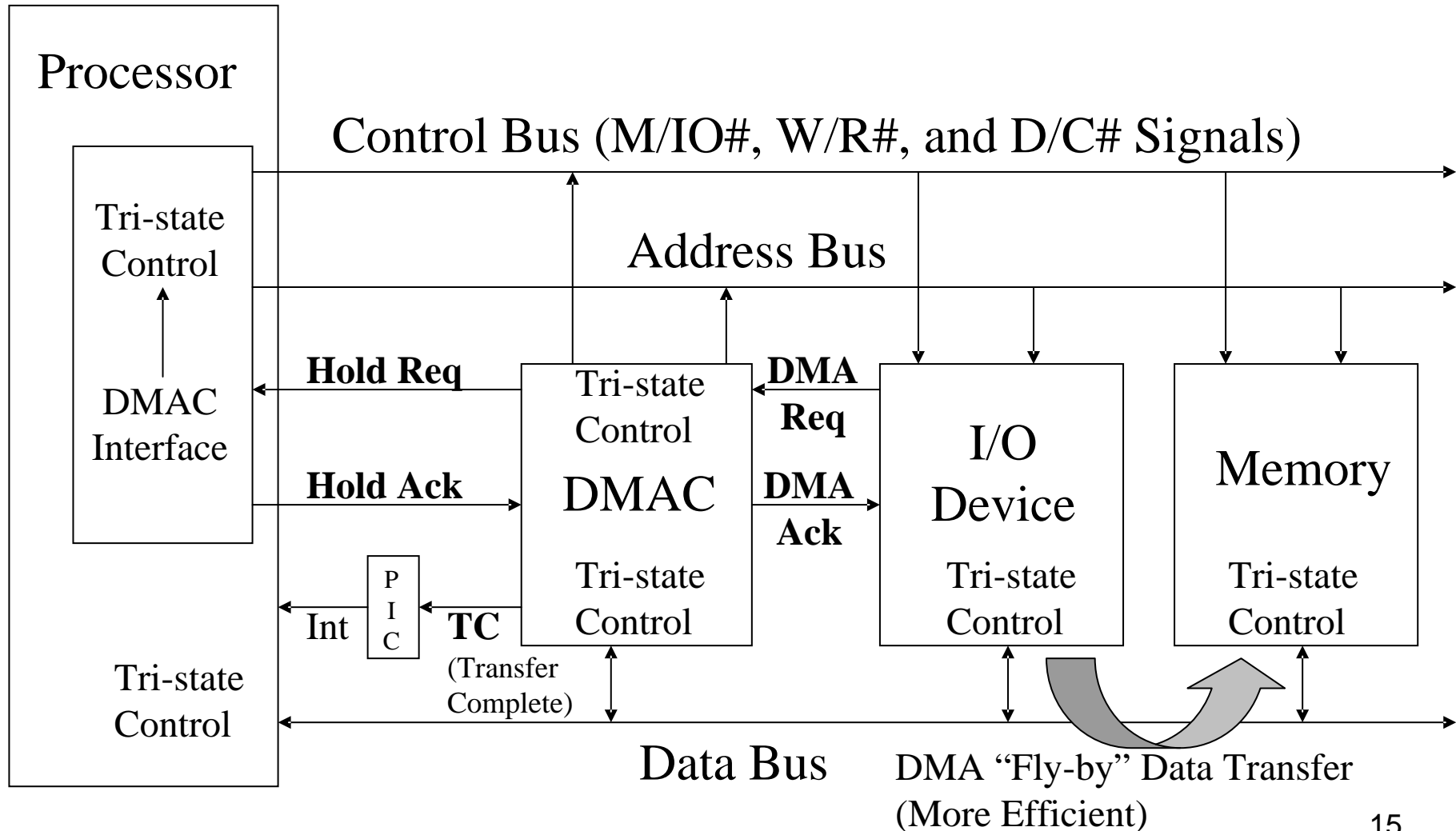
# Direct Memory Access

- We add a DMA Controller (DMAC) to our system, e.g. Intel 8237A DMA controller chip
- The DMAC has the capability of becoming the bus master on the address and control bus for one or more “channels” transferring data between an I/O device and memory, e.g. 8237A supports 4 channels
- We connect DMA Request and DMA Acknowledge signals between the I/O device and the DMAC
- Software in the CPU sets up the DMAC to transfer an entire sequence of bytes between memory buffer and the I/O device or vice versa
- During each byte transfer, the DMAC drives address and control bus signals instead of the processor

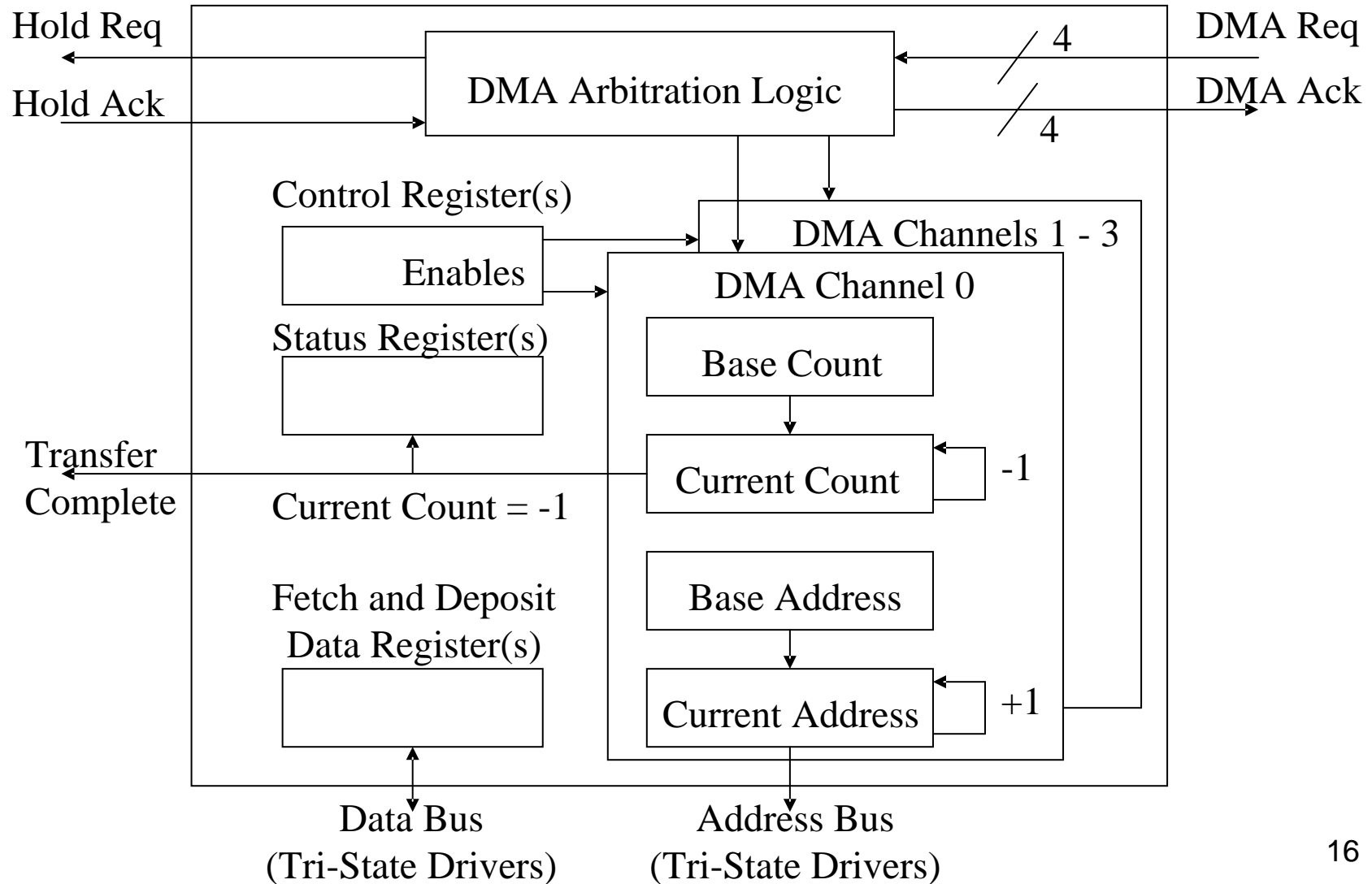
# Direct Memory Access



# Direct Memory Access



# DMA Controller Details





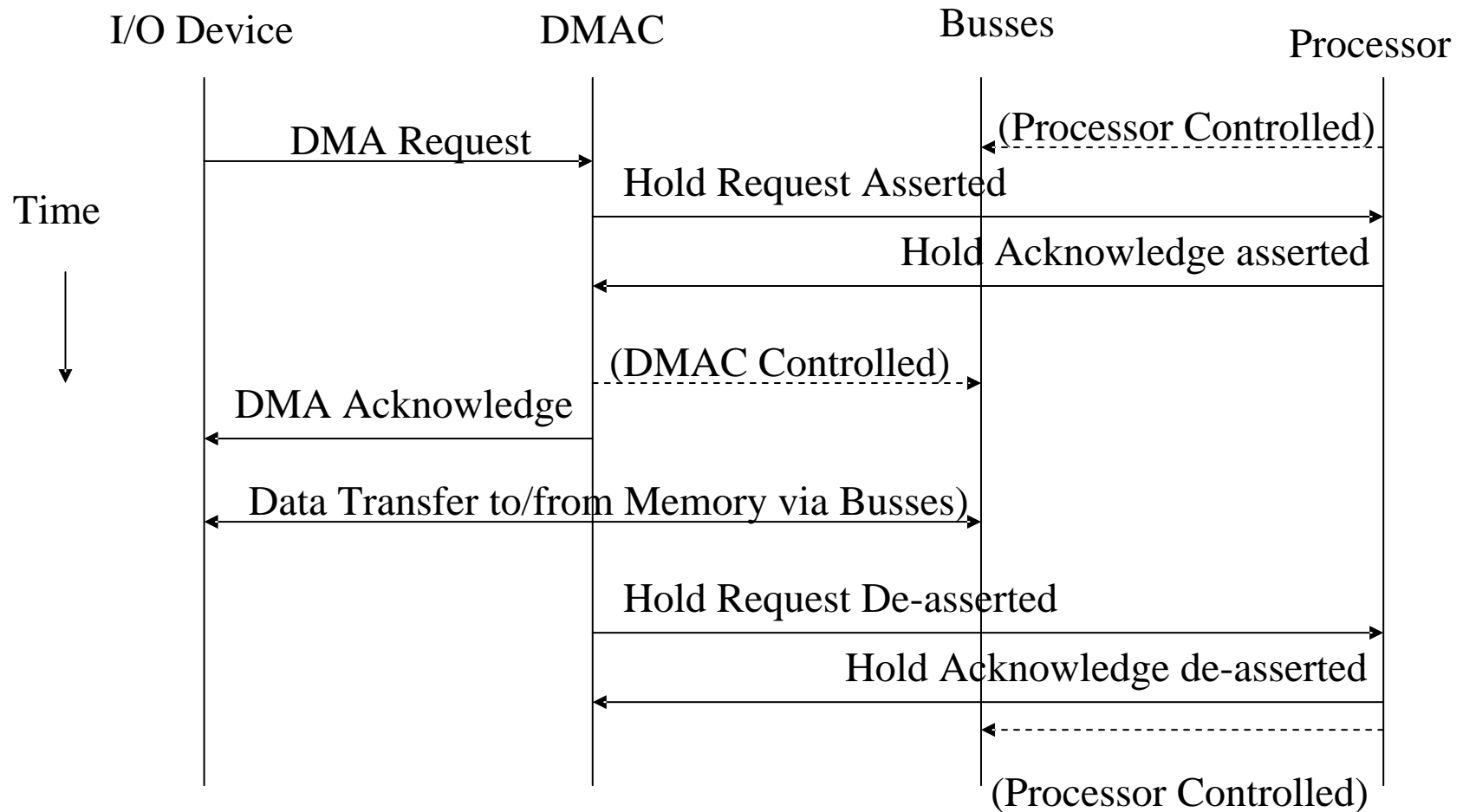
# DMAC Programming

- Generalized Steps for Programming DMAC
  - Allocate a suitably-sized memory buffer
  - Disable the DMA channel being programmed  
(Note that cli does not stop DMA cycle stealing)
  - Set the Base Address Register with buffer address
  - Set the Base Count Register with size of transfer
  - Set the DMA transfer mode
  - Enable the DMA channel to start the transfer

# DMAC Operation

- When requested, the DMAC arbitrates with the CPU to be the master on the address and control busses
- It executes a bus cycle to transfer a byte of data from memory (or I/O device) to I/O device (or memory)
- While DMA controller is bus master, the CPU can not access memory or I/O devices
- This is called “Cycle Stealing” (the DMA controller steals bus cycles from the processor)
- It takes less time than executing an ISR for each byte

# DMAC Bus Arbitration



# DMAC Operation

- When the DMAC finishes transferring an entire block of data between I/O device and memory
  - It interrupts the processor (via TC to the PIC)
  - ISR software in the processor sets up DMAC again for transferring the next block of data
- Processor gets interrupted for I/O handling much less often than once per byte of data
- Hence, much better processor performance

# Tri-State Bus Summary

- All devices have tri-state logic connections to the data bus – may be driving or receiving
- Memory and I/O devices don't need tri-state logic on address/control bus (never drive them)
- Because the processor may need to yield the control/address busses, it must have tri-state logic for driving those bus signals
- DMAC controller must have tri-state logic for driving the control and address bus signals