#### Homework

• Reading

– PAL, pp 201-216, 297-312

- Machine Projects
  - Finish mp2warmup
    - Questions?
  - Start mp2 as soon as possible
- Labs

– Continue labs with your assigned section

- An assembly language programmer handles a lot of details to coordinate the code for calling a function and the code in the function itself
- There are two mechanisms in the instruction set for calling and returning from functions:
- Linux system calls and returns int \$0x80 and iret
- C library style function calls and returns call and ret

- A really "old school" way to pass data back and forth between assembly language functions is to leave all data in "global memory"
- This was really very efficient back when CPU's were not very powerful and some did not have hardware supported stack mechanisms
- Today we understand the software maintenance problem that this choice creates and the CPU's are powerful enough for us to not need to do it

- A somewhat "old school" way to call functions:
  - Load up registers with input values (if any) before call
  - Unload return values (if any) from registers after return
- This is still in use in Linux system calls, such as:
  # <unistd> write as a Linux system call
  movl \$4, %eax
  movl \$4, %eax
  movl \$1, %ebx
  movl \$1, %ebx
  movl \$1, %ebx
  movl \$0utput, %ecx
  movl \$0utput, %ecx
  movl \$len, %edx
  length
  int \$0x80
  all to system

- We won't use the Linux system call and return mechanism in this course, but:
  - I feel that you should be aware of it and recognize it when the textbook uses it in an example
  - We'll use the iret instruction later with hardware interrupts
- We will use the call and ret mechanism as is typically used for C library function calls

#### Call/Return to/from our C Function

- # C compiler generated code for:
- # static int z = mycode(x, y);
  - .text
  - • •
  - pushl y pushl x call \_mycode addl \$8, %esp movl %eax, z
    - # put arg y on stack
      # put arg x on stack
      # call function mycode
      # purge args from stack
      # save return value

- . data
- Z:
  - .long 0 # location for variable z

- Use same function name as used in the calling C program except add a leading underscore '\_'
- Setup C compiler stack frame (optional)
- Use only %eax, %ecx, and %edx to not affect registers the C compiler expects to be preserved
- Save/restore any other registers on stack if used
- Put return value in %eax
- Remove C compiler stack frame (optional)
- Return

• Example of Assembly code for C function: int mycode(int x, int y) {

```
/* automatic variables */
int i;
int j;
. . .
return result;
```

}

- Start with basic calling sequence discussed earlier
  - .text
  - .globl \_mycode
  - \_mycode:
    - ...
      movl xxx, %eax
      ret
      .end

- # entry point label
- # code as needed
- # set return value
- # return to caller

- If function has arguments or automatic variables (that require n bytes), include this optional code
- Assembly language after entry point label (enter):
  - pushl %ebp # set up stack frame
    movl %esp,%ebp # save %esp in %ebp
    subl \$n,%esp # automatic variables
- Assembly language before ret (leave):
  - movl%ebp, %esp# restore %esp from %ebppopl%ebp# restore %ebp

## C Compiler Reserved Registers

- The C compiler assumes it can keep data in certain registers (%ebx, %ebp) when it generates code
- If assembly code uses compiler's reserved registers, it must save and restore the values for the calling C code
- Example:



• State of the stack during function execution:



## Turning It Around

- Calling a C function from Assembly Language
  - Can use printf to help debug assembly code (although it's better to use either tutor or gdb as a debugger)
  - Assume C functions "clobber" the contents of the %eax, %ecx, and %edx registers
  - -If you need to save them across a C function call:
    - Push them on the stack before the call
    - Pop them off the stack after the return

#### Printing From Assembler

• The C calling routine (helloc.c according to our convention) to get things going is:

```
extern void hello();
int main(int argc, char ** argv)
{
    hello();
    return 0;
}
```

#### Printing From Assembler

• Assembly code to print Hello:

.globl hello .text hello: pushl \$hellostr # pass string argument call printf # print the string addl \$4, %esp # restore stack ret .data hellostr: .asciz "Hello\n" # printf format string .end

#### Printing from Assembler

• Assembly code to use a format statement and variable:

#### Preserving Compiler Scratch Registers

- C compiler assumes that it can use certain registers when it generates code (%eax, %ecx, and %edx)
- A C function may or may not clobber the value of these registers
- If assembly code needs to preserve the values of these registers across a C function call, it must save/restore their:

| • • • |                      | <pre># if ecx is in use</pre> |
|-------|----------------------|-------------------------------|
| pushl | <sup>o</sup> ecx     | # save %ecx                   |
| call  | _cFunction           | <pre># may clobber ecx</pre>  |
| popl  | <sup>_</sup><br>⊗ecx | # restore %ecx                |
| • • • |                      | # ecx is OK again             |

## Integrating C and Assembly

- Pick up the makefile from ~bobw/cs341/mp2
- Always read the makefile for a program first!
- The makefile expects a "matched pair" of source names
  - C driver filename is mycodec.c
  - Assembly filename is mycode.s
- The make file uses macro substitutions for input:
  - The format of the make command is:

make A=mycode

Note: Examples are located in: ~bobw/cs341/examples/lecture06

#### Example: Function cpuid

```
• C "driver" in file cpuidc.c to execute code in cpuid.s
   /* cpuidc.c - C driver to test cpuid function
    * bob wilson - 1/15/2012
    */
   #include <stdio.h>
   extern char *cpuid(); /* our .s file is external*/
   int main(int argc, char **argv)
   {
     printf("The cpu ID is: %s\n", cpuid());
     return 0;
   }
```

#### Example: Function cpuid

- Assembly code for function in file cpuid.s
  - # cpuid.s C callable function to get cpu ID value
     .data
    buffer:

```
.asciz "Overwritten!" # overwritten later
    .text
    .globl cpuid
cpuid:
    movl $0,%eax
                          # zero to get Vendor ID
                          # get it
    cpuid
    movl $buffer, %eax
                         # point to string buffer
    movl %ebx, (%eax) # move four chars
    movl %edx, 4(%eax) # move four chars
    movl %ecx, 8(%eax) # move four chars
                          # string pointer is in %eax
     ret.
     .end
```

# Self Modifying Code 😕

• Our assembler does not actually support cpuid instruction, so I made the code self-modifying:

cpuid:

movb \$0xa2, cpuid2 movl \$0,%eax

cpuid1:

nop

cpuid2:

nop

movb \$0x0f, cpuid1 # patch in the cpuid first byte # patch in the cpuid second byte # input to cpuid for ID value # hex for cpuid instruction here # 0x0f replaces 0x90

# 0xa2 replaces 0x90

# Self Modifying Code 🟵

- Obviously, the self modifying code I used for this demonstration would not work if:
  - The code is physically located in PROM/ROM
  - There is an O/S like UNIX/Linux that protects the code space from being modified (A problem that we avoid using the Tutor VM)
- Try justifying the "kludge" in the next slide to the maintenance programmer!!

#### Self Modifying Code in C $\ensuremath{\mathfrak{S}}$

int main(int argc, char \*\*args)

{

char function [100]; // array to hold the machine code bytes of the function

// I put machine code instructions byte by byte into the function array: // Instruction 1: movl the &function[6] to the %eax (for return value) // Instruction 2: the machine code for a ret instruction (0xc3) // Following the ret instruction, I put the bytes of the string "Hello World" // with a null terminator into the array starting at function[6]

```
// execute the function whose address is the array
printf("%s\n", (* (char * (*)()) function) ());
return 0;
}
```