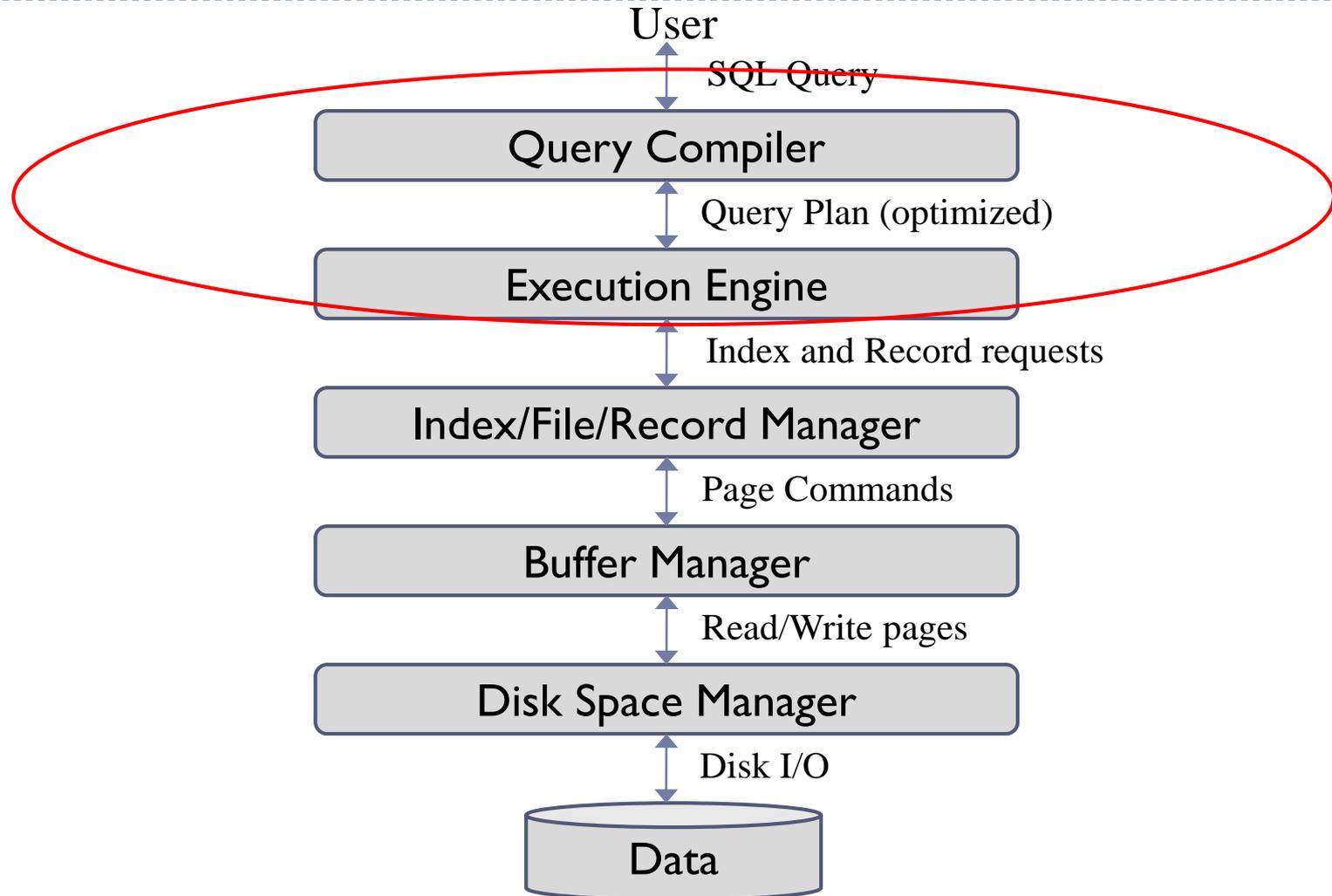


Query Evaluation Overview, cont.

Lecture 9

Architecture of a DBMS



The two major parts of the DB engine

- ▶ QP = query processor, top two boxes on last slide
- ▶ Storage manager = rest of boxes
- ▶ See “index and record requests” flowing between
- ▶ Can be more specific, see list, pg. 283:
- ▶ Actions on “files”: file scan, search with equality selection, search with range selection, insert record, delete record
- ▶ Files listed: heap files, sorted files, clustered files, heap file with unclustered tree index, heap file with unclustered hash index. An index on its own is a sorted file.
- ▶ A file is something that the storage engine can process via an ISAM-like API
- ▶ A table can be accessed as a file: pick an index for it (or not)



Storage Engine API

- ▶ If a QP and storage engine hue to an API, then different storage engines can be “plugged in” to the database
- ▶ Example: MS SQL Server can access Excel files via the OLE-DB API. Also via ODBC.
 - ▶ That is, there is an Excel OLE-DB “provider” (you don’t need the whole Excel GUI).
- ▶ Example: MySQL has various storage engines—MyISAM and Innodb, etc.
 - ▶ New one (Nov ‘12): ClouSE uses Amazon S3 cloud storage.



MySQL Storage Engine API

Top-level API (subset) from [internals manual](#)

Note handoff to TABLE object for data actions:

```
int (*commit)(THD *thd, bool all);
```

```
int (*rollback)(THD *thd, bool all);
```

```
int (*prepare)(THD *thd, bool all);
```

```
int (*recover)(XID *xid_list, uint len);
```

```
handler *(*create)(TABLE *table); ←next slide
```

```
void (*drop_database)(char* path);
```

```
bool (*flush_logs)();
```



MySQL Storage Engine API: TABLE API

[22.18.1 bas_ext](#)

[22.18.2 close](#)

[22.18.3 create](#)

[22.18.4 delete_row](#)

[22.18.5 delete_table](#)

[22.18.6 external_lock](#)

[22.18.7 extra](#)

[22.18.8 index_end](#)

[22.18.9 index_first](#)

[22.18.10 index_init](#) Set current index

[22.18.11 index_last](#)

[22.18.12 index_next](#)

[22.18.13 index_prev](#)

} Index
scan

[22.18.14 index_read](#)

[22.18.15 index_read_idx](#)

[22.18.16 index_read_last](#)

[22.18.17 info](#)

[22.18.18 open](#)

[22.18.19 position](#)

[22.18.20 records_in_range](#)

[22.18.21 rnd_init](#)

[22.18.22 rnd_next](#)

[22.18.23 rnd_pos](#)

[22.18.24 start_stmt](#)

[22.18.25 store_lock](#)

[22.18.26 update_row](#)

[22.18.27 write_row](#)

} Table
scan

Insert row

Set current index: only one allowed for
the index scan



Access Paths

- ▶ An **access path** is a method of retrieving tuples:
 - ▶ File scan (AKA table scan if on a table)
 - ▶ Index scan using an index that **matches** a condition
 - ▶ As just seen in mysql, only one index is involved in an index scan.
- ▶ A tree index **matches** (a conjunction of) terms that involve **every** attribute in a **prefix** of the search key
 - ▶ E.g., tree index on $\langle a, b, c \rangle$ matches the selection $a=5 \text{ AND } b=3$, and $a=5 \text{ AND } b>6$, but not $b=3$
- ▶ A hash index **matches** (a conjunction of) terms **attribute = value** for **every** attribute in the search key of the index
 - ▶ E.g., hash index on $\langle a, b, c \rangle$ matches $a=5 \text{ AND } b=3 \text{ AND } c=5$
 - ▶ but it does not match $b=3$, or $a=5 \text{ AND } b=3$



Example of matching indexes

Pg. 399: fix error Sailors → Reserves on line 8

Reserves (sid: integer, bid: integer, day: dates, rname: string) ←
rname column added here

with indexes:

- ▶ Index1: Hash index on (rname, bid, sid)
 - ▶ Matches: rname='Joe' and bid = 5 and sid=3
 - ▶ Doesn't match: rname='Joe' and bid = 5
- ▶ Index2: Tree index on (rname, bid, sid)
 - ▶ Matches: rname='Joe' and bid = 5 and sid=3
 - ▶ Matches: rname='Joe' and bid = 5, also rname = 'Joe'
 - ▶ Doesn't match: bid = 5
- ▶ Index3: Tree index on (rname)
- ▶ Index4: Hash index on (rname)
 - ▶ These two match any conjunct with rname='Joe' in it



Executing Selections

- ▶ Find the *most selective access path*, retrieve tuples using it
 - ▶ Then, apply any remaining terms that don't match the index
- ▶ *Most selective access path*: index or file scan **estimated** to require the fewest page I/Os
 - ▶ Consider *day<8/9/94 AND bid=5 AND sid=3*
- ▶ If we have B+ tree index on *day*, can use that access path
 - ▶ Then, *bid=5* and *sid=3* must be checked for each retrieved tuple
 - ▶ *day* condition is **primary conjunct** (matches index in use)
- ▶ Alternatively, use hash index on *<bid, sid>* for the index scan
 - ▶ Then, *day<8/9/94* must then be checked
- ▶ *Need to estimate I/Os to decide between these*



Example Schema

Sailors (*sid*: integer, *sname*: string, *rating*: integer, *age*: real)

Reserves (*sid*: integer, *bid*: integer, *day*: dates, *rname*: string)

- ▶ Similar to old schema; *rname* added
- ▶ Reserves:
 - ▶ 40 bytes long tuple, 100K records, 4KB pages
 - ▶ So $100K * 40 = 4MB$ data, $4MB / 4KB = 1000$ pages
 - ▶ Assume 4000 bytes/pg, so 100 tuples per page
- ▶ Sailors:
 - ▶ 50 bytes long tuple, 40K tuples, 4KB pages
 - ▶ So 80 tuples per page, 500 pages



Using an Index for Selections

- ▶ Cost influenced by:

- ▶ Number of qualifying tuples
- ▶ Whether the index is **clustered** or not

- ▶ Ex:

```
SELECT *  
FROM Reserves R  
WHERE R.rname < 'C%'
```

- ▶ Assuming uniform distribution of names, 2/26 ~10% of tuples qualify, that is 10000 tuples (pg. 401)

- ▶ With a clustered index, cost is little more 100 I/Os:
 - ▶ $10000 \times 40 = 400\text{KB}$ data, in 100 data pages, plus a few index pgs
- ▶ If not clustered, up to 10K I/Os!
 - ▶ About 10000 data pages accessed, each with own I/O (unless big enough buffer pool)
 - ▶ Better to do a table scan: 1000 pages, so 1000 I/Os.



Executing Projections

- ▶ Expensive part is removing duplicates
 - ▶ DBMS don't remove duplicates unless **DISTINCT** is specified

```
SELECT  DISTINCT R.sid, R.bid
FROM    Reserves R
```

- ▶ **Sorting Approach**
 - ▶ Sort on <sid, bid> (or <bid, sid>) and remove duplicates
 - ▶ Avoidable if an index with R.sid and R.bid in the search key exists
- ▶ **Hashing Approach**
 - ▶ Hash on <sid, bid> to create partitions (buckets)
 - ▶ Load partitions into memory one at a time, build in-memory hash structure, and eliminate duplicates



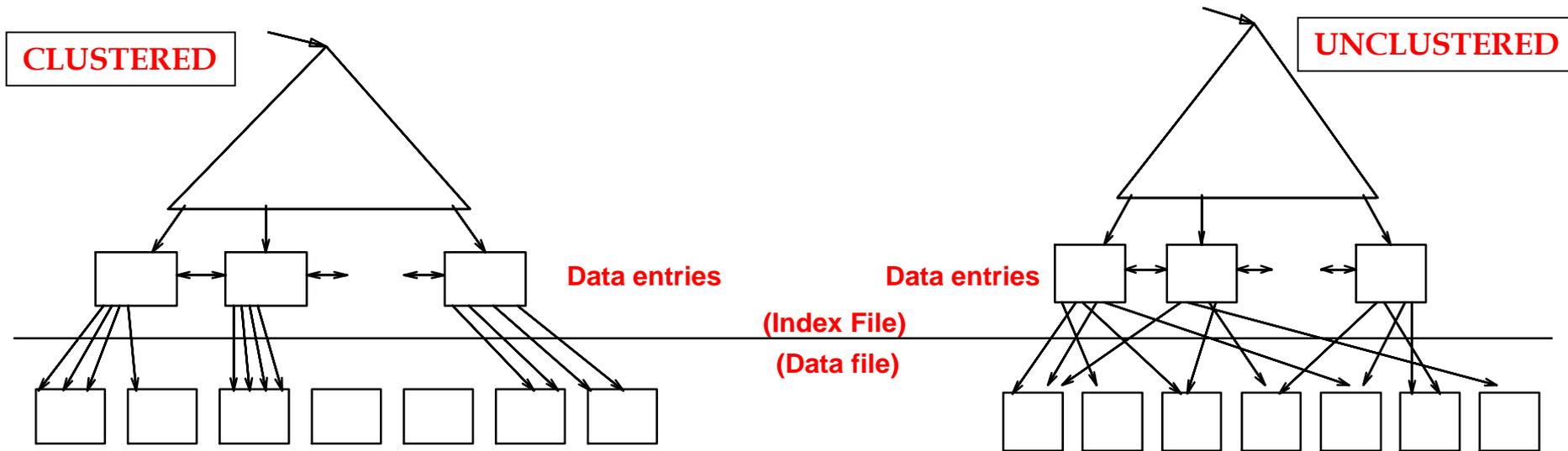
Executing Joins: Index Nested Loops

```
foreach tuple r in R do
    foreach tuple s in S where r_i == s_j do
        add <r, s> to result
```

- ▶ **Cost = $(M * p_R) * (\text{cost of finding matching inner-table tuples})$**
- ▶ **M** = number of pages of R, **p_R** = number of R tuples per page
- ▶ **If relation has index on join attribute, make it inner relation**
 - ▶ For each outer tuple, cost of probing inner index is 1.2 for hash index, 2-4 for B+, plus cost to retrieve matching S tuples
 - ▶ **Clustered index** typically single I/O (Alt 2) or no more I/O (Alt 1) (unless many matching S tuples)
 - ▶ **Unclustered index** 1 I/O per matching S tuple



From class 5/Chap. 8: Clustered Index



- ▶ To build clustered (tree) index, first sort the heap file, leaving some free space on each page for future inserts
- ▶ Overflow pages may be needed for inserts
 - ▶ Hence order of data records is **close to** the sort order
- ▶ This is an **Alternative 2** clustered index. For Alternative 1, the rows are *in* the data entries, so the original index lookup (tree or hash) finds the whole row.
- ▶ Oracle index-organized tables and mysql primary key indexes are Alt 1 clustered.

Duplicate keys in indexes

- ▶ B trees: see Sec. 10.7 Duplicates: two ways to go—
 - ▶ Overflow pages, but not “typical”
 - ▶ Just sequential entries with the same key (we’ll assume this)
- ▶ Extendible Hashing: uses overflow pages (pg. 379)
- ▶ Linear Hashing: uses multiple entries in the main pages.
 - ▶ May involve “extra” overflow pages, since splitting doesn’t help with a long sequence of same-key entries.
- ▶ Shouldn’t use a hash index on a low-cardinality column. B-tree is OK (esp. Alt. 3). (Bitmap index is best.)
- ▶ Cost of access for all dups of one key: calculate number of pages of duplicate index entries



Example of Index Nested Loops (1/2)

Example: Reserves JOIN Sailors (natural join on sid)

Case 1: Hash-index (Alternative 2) on *sid* of Sailors

- ▶ Choose Sailors as inner relation
- ▶ Scan Reserves: 100K tuples, 1000 page I/Os
- ▶ For each Reserves tuple
 - ▶ 1.2 I/Os to get data entry in index (see pg. 402, 412)
 - ▶ 1 I/O to get (the exactly one) matching Sailors tuple (primary key)
- ▶ Total: **221,000 I/Os**
 - ▶ unless Sailors, 500 pages, fits in buffer pool along with some/all of Reserves, 1000 pages, then only 1500 I/Os
 - ▶ Dbs3: 24GB in buffer pool = 3M 8KB pages = 6M 4KB pages!
 - ▶ But for textbook queries, assume only hundreds of buffer pages.



Example of Index Nested Loops (2/2)

Example: Reserves JOIN Sailors (natural join on sid)

Case 2: Hash-index (Alternative 1 or 2) on *sid* of Reserves

- ▶ Choose Reserves as inner
- ▶ Scan Sailors: 40K tuples, 500 page I/Os
- ▶ For each Sailors tuple
 - ▶ 1.2 I/Os to find index page with data entries
 - ▶ Assuming uniform distribution, 2.5 matching records per sailor
 - ▶ Cost of retrieving records is nothing further (Alt. 1 clustered) or 1 (Alt. 2 clustered) or 2.5 I/Os (Alt. 2 unclustered)
- ▶ Total: **48,500 I/Os** (clustered, alt. 1) **88,500 I/Os** (clustered, alt. 2) or **148,500 I/Os** (unclustered)
 - ▶ Again assuming the buffer pool can't contain the whole tables



Executing Joins: Sort-Merge

- ▶ Sort R and S on the join column (sid, PK of S)
 - ▶ Then scan them to do a **merge** on join column
- ▶ S is scanned once, each row has unique sid
- ▶ Each R **group** (a certain sid) is scanned once
 - ▶ Here only 2.5 records/group on average
- ▶ **Cost: $M \log M + N \log N + (M+N)$** (as we will see later)
 - ▶ Text, pg. 403, estimates cost at 7500 I/Os for this example
 - ▶ So better not to use the index in this case!
 - ▶ Note the tables are roughly the same size, the sweet spot for sort-merge join.



System R Optimizer

- ▶ Developed at IBM starting in the 1970's
 - ▶ Most widely used currently; works well for up to 10 joins
- ▶ **Cost estimation**
 - ▶ Statistics maintained in system catalogs
 - ▶ Used to estimate cost of operations and result sizes
 - ▶ Considers combination of CPU and I/O costs
- ▶ **Query Plan Space**
 - ▶ Only the space of **left-deep plans** is considered
 - ▶ Cartesian products avoided

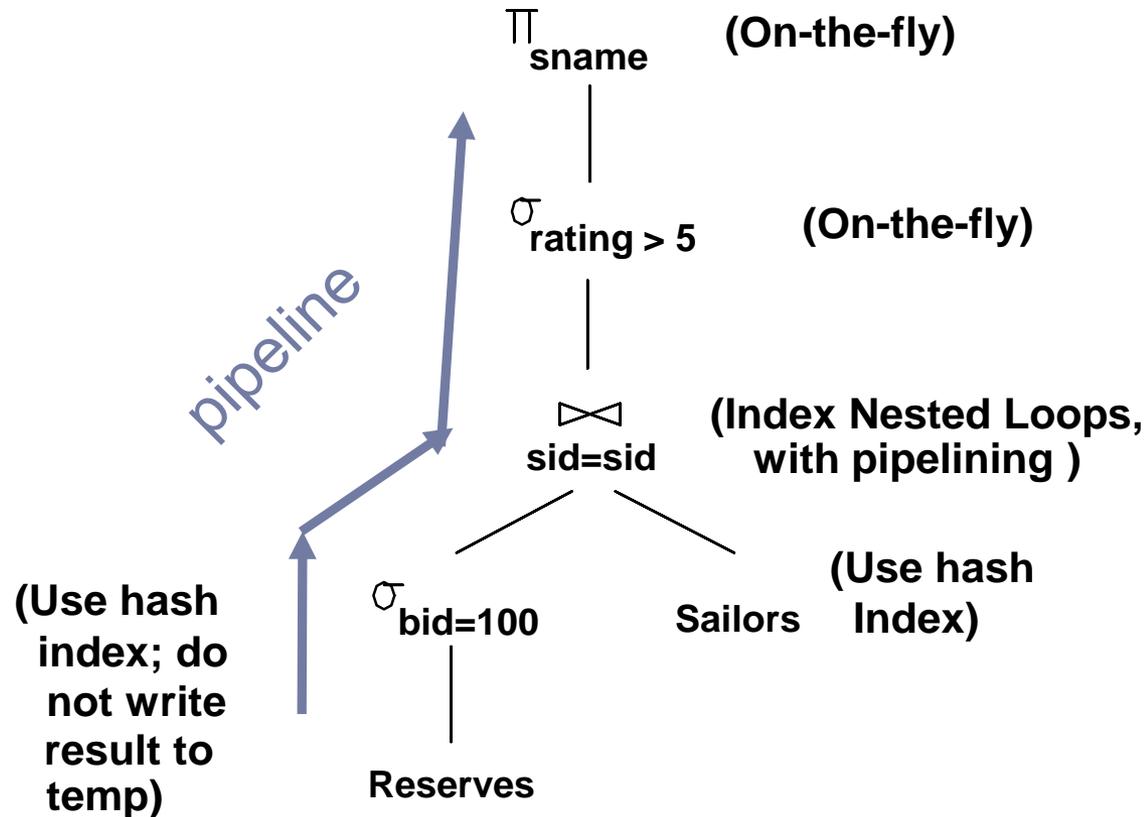


Left Deep Trees

- ▶ Consider nested-loop joins
- ▶ Inner tables need to be materialized because they are probed repeatedly for each row of the outer table
 - ▶ Materialized means available as a table, not just a stream of rows, so can be probed by PK index.
- ▶ Left table = outer table
- ▶ Left table can be pipelined: rows used one at a time in order (i.e., doesn't need to be materialized)
- ▶ So Left-deep plans allow output of each operator to be **pipelined** into the next operator without storing it in a temporary relation
- ▶ i.e., Left Deep trees can be “fully pipelined”
- ▶ See pg. 407 for a two-join example



Example of join with left table pipelined and right table materialized



Cost Estimation

For each plan considered, must estimate:

- ▶ **Cost of each operator in plan tree**
 - ▶ Depends on input cardinalities
 - ▶ Operation and access type: sequential scan, index scan, joins
- ▶ **Size of result for each operation in tree**
 - ▶ Use information about the input relations
 - ▶ For selections and joins, assume independence of predicates



Size Estimation and Reduction Factors

```
SELECT attribute list  
FROM relation list  
WHERE term1 AND ... AND termk
```

- ▶ Maximum number of tuples is cardinality of cross product
- ▶ **Reduction factor (RF)** associated with each *term* reflects its impact in reducing result size
 - ▶ Implicit assumption that *terms are independent!*
 - ▶ *col = value* has $RF = 1/NKeys(I)$, given index *I* on *col*
 - ▶ *col 1 = col 2* has $RF = 1/\max(NKeys(I 1), NKeys(I 2))$
 - ▶ *col > value* has $RF = (\text{High}(I) - \text{value}) / (\text{High}(I) - \text{Low}(I))$



Example Schema

Sailors (*sid*: integer, *sname*: string, *rating*: integer, *age*: real)

Reserves (*sid*: integer, *bid*: integer, *day*: dates, *rname*: string)

- ▶ Similar to old schema; *rname* added
- ▶ Reserves:
 - ▶ 40 bytes long tuple, 100K records, 100 tuples per page, 1000 pages
- ▶ Sailors:
 - ▶ 50 bytes long tuple, 40K tuples, 80 tuples per page, 500 pages

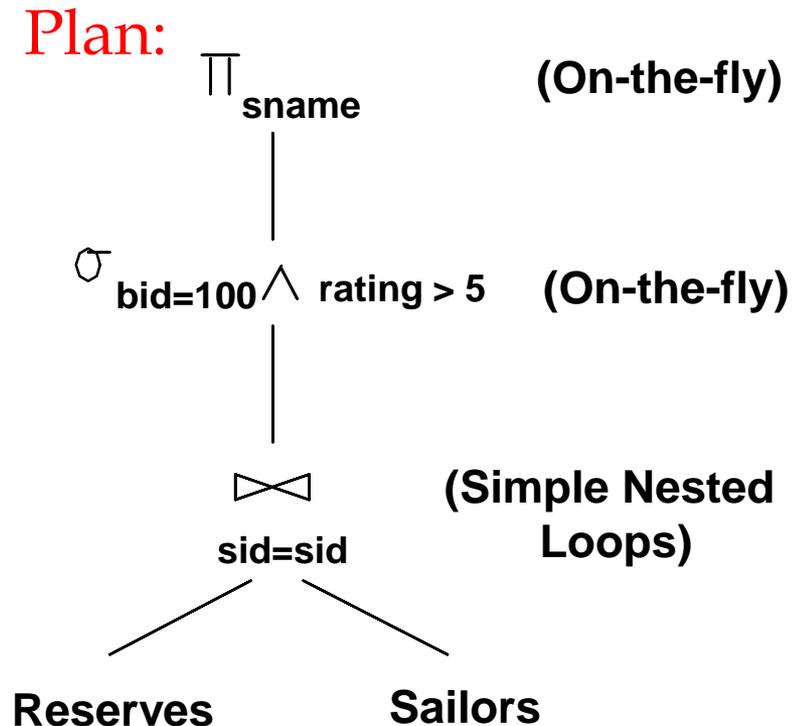


Evaluation Example

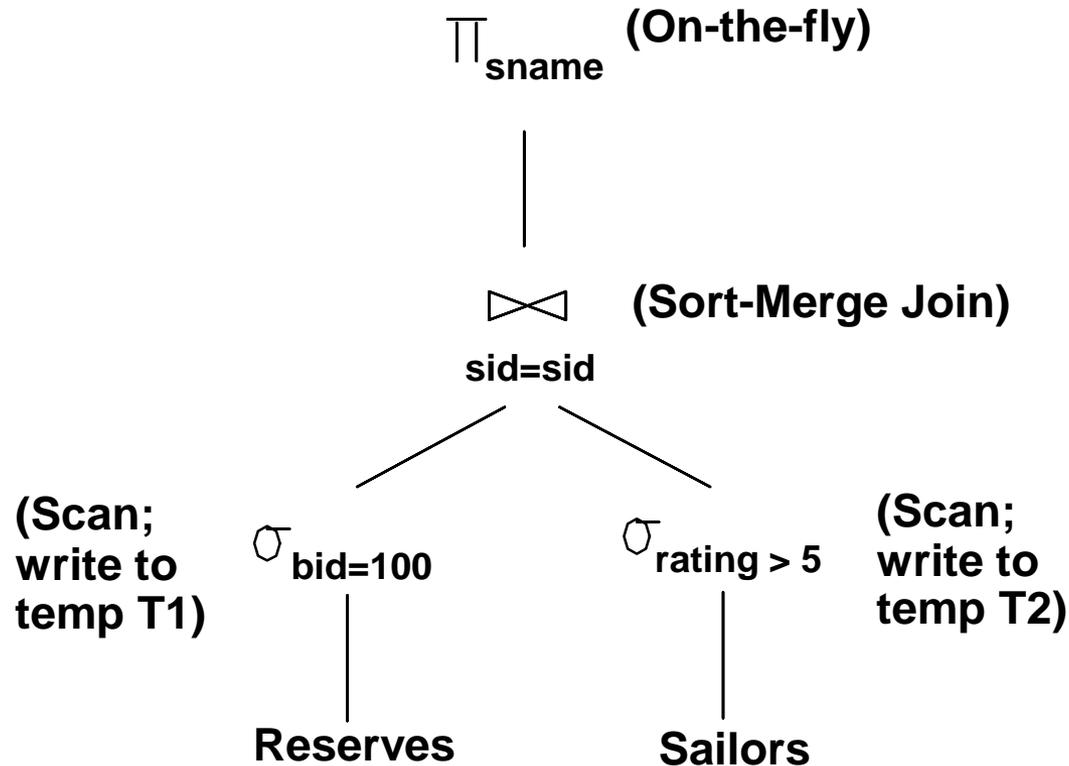
```
SELECT S.sname
FROM Reserves R, Sailors S
WHERE R.sid=S.sid AND
      R.bid=100 AND S.rating>5
```

Cost: 1000+100*1000*500 I/Os

- ▶ R's 1000 pages have 100*1000 rows each of which causes a scan of S
- ▶ By no means the worst plan!
- ▶ Misses several opportunities:
 - ▶ Selections could have been 'pushed' earlier
 - ▶ No use of any available indexes



Alternative Plan 1 (No Indexes)

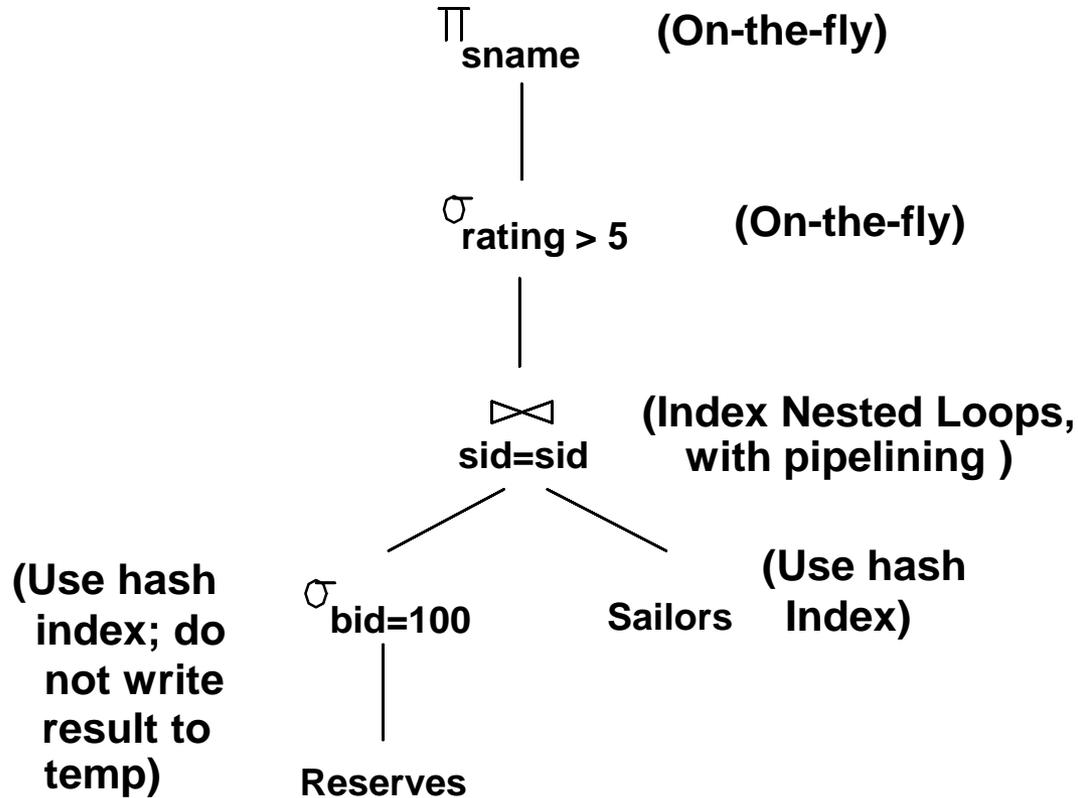


Alternative Plan 1 (No Indexes)

- ▶ Main difference: **push down selections**
 - ▶ Scan Reserves (1000) + write temp T1 (10 pages, if we have 100 boats, uniform distribution)
 - ▶ Scan Sailors (500) + write temp T2 (250 pages, if we have 10 ratings)
 - ▶ Sort-merge join T1 and T2
 - ▶ Assume there are 5 buffers:
 - ▶ Sort T1 ($2 \times 2 \times 10$), Sort T2 ($2 \times 4 \times 250$), Merge ($10 + 250$)
 - ▶ **Total: 4060 page I/Os**
-



Alternative Plan 2 (With Indexes)



Alternative Plan 2 (With Indexes)

- ▶ With clustered index on *bid* of Reserves, we get $100,000/100 = 1000$ tuples on $1000/100 = 10$ pages
- ▶ Inner Nested Loop join with **pipelining (result not materialized)**
- ▶ Join column *sid* is a key for Sailors
 - ▶ At most one matching tuple, unclustered index on *sid* OK
- ▶ Decision not to push *rating*>5 before the join is based on availability of *sid* index on Sailors
- ▶ **Cost:**
 - ▶ Selection of Reserves tuples 10 I/Os
 - ▶ For each, must get matching Sailors tuple ($1000*1.2$)
 - ▶ Total **1210 I/Os**



Summary

- ▶ There are several alternative evaluation algorithms for each relational operator.
- ▶ A query is evaluated by converting it to a tree of operators and evaluating the operators in the tree.
- ▶ Must understand query optimization in order to fully understand the performance impact of a given database design (relations, indexes) on a workload (set of queries).
- ▶ Two parts to optimizing a query:
 - ▶ Consider a set of alternative plans.
 - ▶ Must prune search space; typically, left-deep plans only.
 - ▶ Must estimate cost of each plan that is considered.
 - ▶ Must estimate size of result and cost for each plan node.
- ▶ *Key issues: Statistics, indexes, operator implementations.*