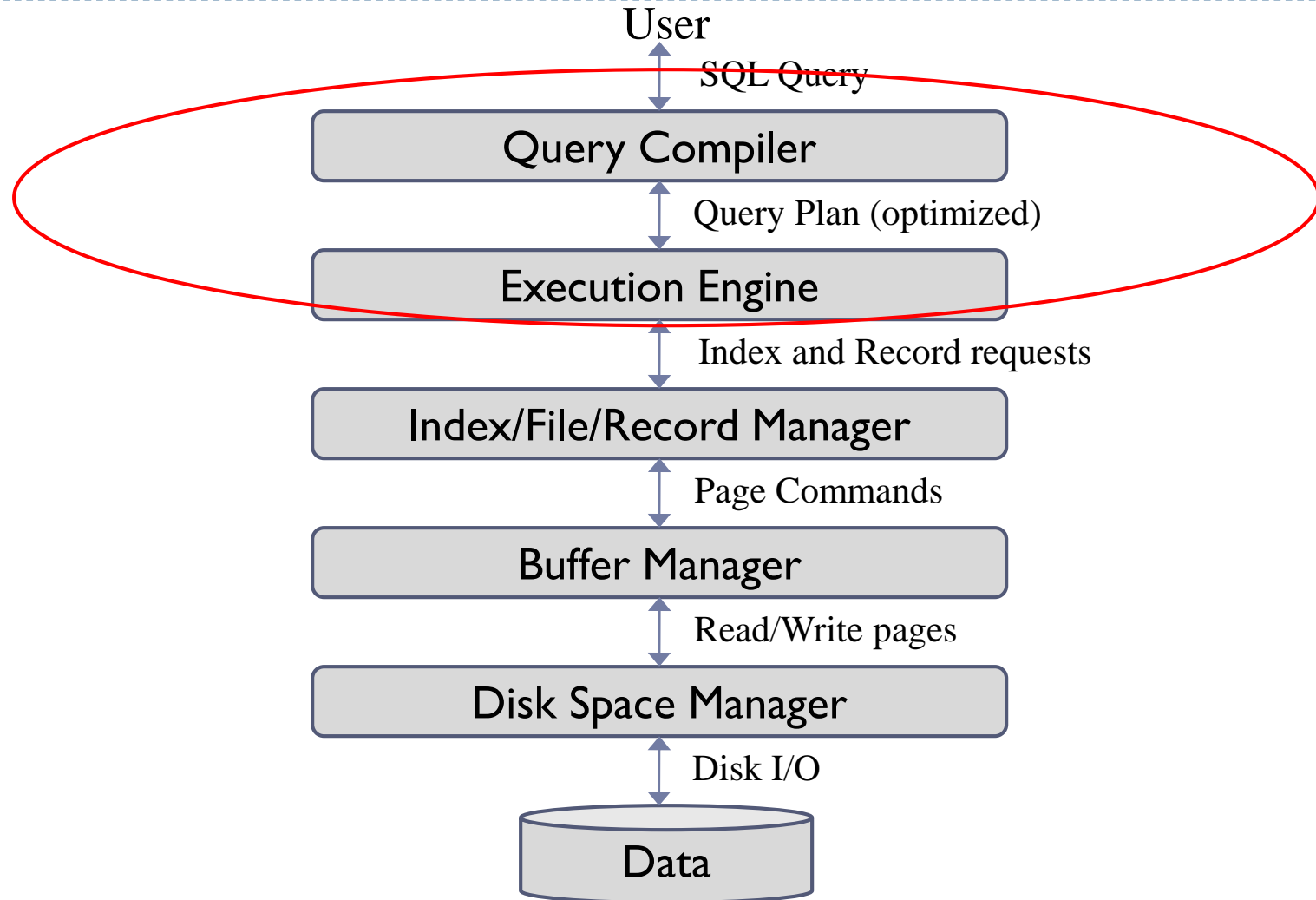


# Query Evaluation Overview, cont.

## Lecture 9

# Architecture of a DBMS

---



# The two major parts of the DB engine

---

- ▶ QP = query processor, top two boxes on last slide
- ▶ Storage manager = rest of boxes
- ▶ See “index and record requests” flowing between
- ▶ Can be more specific, see list, pg. 283:
- ▶ Actions on “files”: file scan, search with equality selection, search with range selection, insert record, delete record
- ▶ Files listed: heap files, sorted files, clustered files, heap file with unclustered tree index, heap file with unclustered hash index. An index on its own is a sorted file.
- ▶ A file is something that the storage engine can process via an ISAM-like API
- ▶ A table can be accessed as a file: pick an index for it (or not)



# Storage Engine API

---

- ▶ If a QP and storage engine hue to an API, then different storage engines can be “plugged in” to the database
- ▶ Example: MS SQL Server can access Excel files via the OLE-DB API. Also via ODBC.
  - ▶ That is, there is an Excel OLE-DB “provider” (you don’t need the whole Excel GUI).
- ▶ Example: MySQL has various storage engines—MyISAM and Innodb, etc.
  - ▶ New one (Nov ‘12): ClouSE uses Amazon S3 cloud storage.



# MySQL Storage Engine API

---

Top-level API (subset) from [internals manual](#)

Note handoff to TABLE object for data actions:

```
int (*commit)(THD *thd, bool all);
```

```
int (*rollback)(THD *thd, bool all);
```

```
int (*prepare)(THD *thd, bool all);
```

```
int (*recover)(XID *xid_list, uint len);
```

```
handler *(*create)(TABLE *table); ←next slide
```

```
void (*drop_database)(char* path);
```

```
bool (*flush_logs)();
```

---



# MySQL Storage Engine API: TABLE API

---

22.18.1 bas\_ext

22.18.2 close

22.18.3 create

22.18.4 delete\_row

22.18.5 delete\_table

22.18.6 external\_lock

22.18.7 extra

22.18.8 index\_end

22.18.9 index\_first

22.18.10 index\_init Set current index

22.18.11 index\_last

22.18.12 index\_next

22.18.13 index\_prev

} Index  
scan

22.18.14 index\_read

22.18.15 index\_read\_idx

22.18.16 index\_read\_last

22.18.17 info

22.18.18 open

22.18.19 position

22.18.20 records\_in\_range

22.18.21 rnd\_init

22.18.22 rnd\_next

22.18.23 rnd\_pos

22.18.24 start\_stmt

22.18.25 store\_lock

22.18.26 update\_row

22.18.27 write\_row

} Table  
scan

Insert row

Set current index: only one allowed for  
the index scan

---



# Access Paths

---

- ▶ An **access path** is a method of retrieving tuples:
  - ▶ File scan (AKA table scan if on a table)
  - ▶ Index scan using an index that **matches** a condition
  - ▶ As just seen in mysql, only one index is involved in an index scan.
- ▶ A tree index **matches** (a conjunction of) terms that involve **every** attribute in a **prefix** of the search key
  - ▶ E.g., tree index on **<a, b, c>** matches the selection **a=5 AND b=3**, and **a=5 AND b>6**, but not **b=3**
- ▶ A hash index **matches** (a conjunction of) terms **attribute = value** for **every** attribute in the search key of the index
  - ▶ E.g., hash index on **<a, b, c>** matches **a=5 AND b=3 AND c=5**
  - ▶ but it does not match **b=3**, or **a=5 AND b=3**



# Example of matching indexes

---

Pg. 399: fix error Sailors → Reserves on line 8

Reserves (sid: integer, bid: integer, day: dates, rname: string) ←  
rname column added here

with indexes:

- ▶ Index1: Hash index on (rname, bid, sid)
  - ▶ Matches: rname='Joe' and bid = 5 and sid=3
  - ▶ Doesn't match: rname='Joe' and bid = 5
- ▶ Index2: Tree index on (rname, bid, sid)
  - ▶ Matches: rname='Joe' and bid = 5 and sid=3
  - ▶ Matches: rname='Joe' and bid = 5, also rname = 'Joe'
  - ▶ Doesn't match: bid = 5
- ▶ Index3: Tree index on (rname)
- ▶ Index4: Hash index on (rname)
  - ▶ These two match any conjunct with rname='Joe' in it





# Executing Selections

---

- ▶ Find the *most selective access path*, retrieve tuples using it
  - ▶ Then, apply any remaining terms that don't match the index
- ▶ *Most selective access path*: index or file scan *estimated* to require the fewest page I/Os
  - ▶ Consider *day<8/9/94 AND bid=5 AND sid=3*
- ▶ If we have B+ tree index on *day*, can use that access path
  - ▶ Then, *bid=5* and *sid=3* must be checked for each retrieved tuple
  - ▶ *day* condition is *primary conjunct* (matches index in use)
- ▶ Alternatively, use hash index on *<bid, sid>* for the index scan
  - ▶ Then, *day<8/9/94* must then be checked
- ▶ *Need to estimate I/Os to decide between these*



# Example Schema

---

Sailors (sid: integer, sname: string, rating: integer, age: real)

Reserves (sid: integer, bid: integer, day: dates, rname: string)

- ▶ Similar to old schema; **rname** added
- ▶ Reserves:
  - ▶ 40 bytes long tuple, 100K records, 4KB pages
  - ▶ So  $100K * 40 = 4MB$  data,  $4MB / 4KB = 1000$  pages
  - ▶ Assume 4000 bytes/pg, so 100 tuples per page
- ▶ Sailors:
  - ▶ 50 bytes long tuple, 40K tuples, 4KB pages
  - ▶ So 80 tuples per page, 500 pages



# Using an Index for Selections

---

- ▶ Cost influenced by:

- ▶ Number of qualifying tuples
- ▶ Whether the index is **clustered** or not

- ▶ Ex:           SELECT \*  
                  FROM   Reserves R  
                  WHERE  R.rname < 'C%'

- ▶ Assuming uniform distribution of names, 2/26 ~10% of tuples qualify, that is 10000 tuples (pg. 401)

- ▶ With a clustered index, cost is little more 100 I/Os:
  - ▶  $10000 \times 40 = 400\text{KB}$  data, in 100 data pages, plus a few index pgs
- ▶ If not clustered, up to 10K I/Os!
  - ▶ About 10000 data pages accessed, each with own I/O (unless big enough buffer pool)
  - ▶ Better to do a table scan: 1000 pages, so 1000 I/Os.



# Executing Projections

---

- ▶ Expensive part is removing duplicates
  - ▶ DBMS don't remove duplicates unless **DISTINCT** is specified

```
SELECT  DISTINCT R.sid, R.bid  
FROM    Reserves R
```

- ▶ **Sorting Approach**
  - ▶ Sort on <sid, bid> (or <bid, sid>) and remove duplicates
  - ▶ Avoidable if an index with R.sid and R.bid in the search key exists
- ▶ **Hashing Approach**
  - ▶ Hash on <sid, bid> to create partitions (buckets)
  - ▶ Load partitions into memory one at a time, build in-memory hash structure, and eliminate duplicates



# Executing Joins: Index Nested Loops

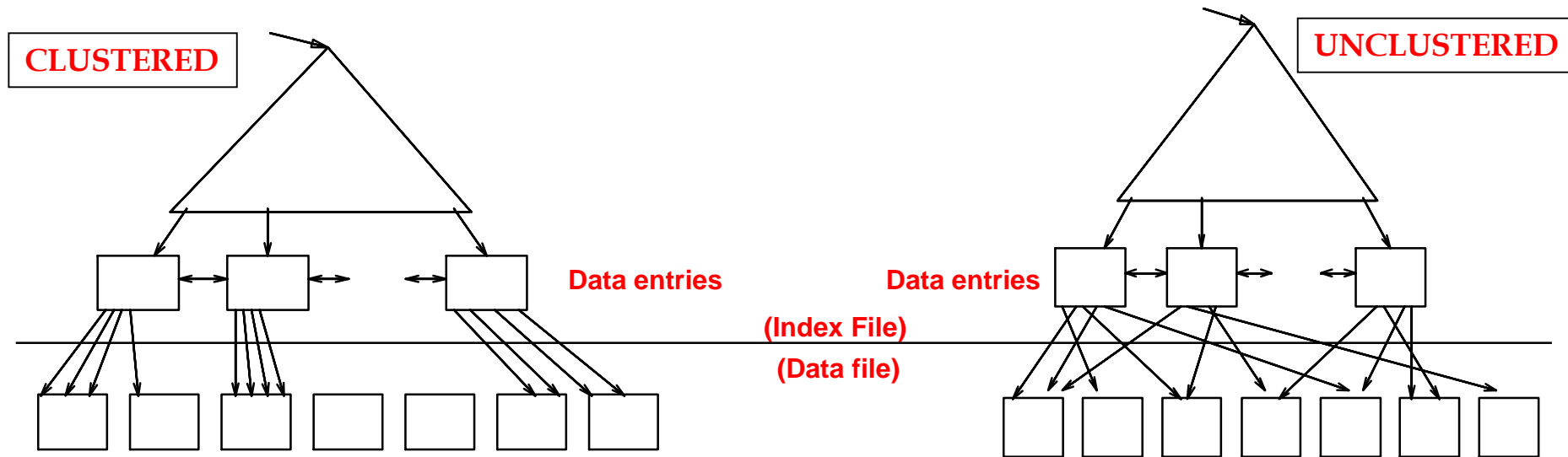
---

```
foreach tuple r in R do
    foreach tuple s in S where  $r_i == s_j$  do
        add  $\langle r, s \rangle$  to result
```

- ▶ **Cost** =  $(M * p_R) * (\text{cost of finding matching inner-table tuples})$
- ▶ **M** = number of pages of R,  **$p_R$**  = number of R tuples per page
- ▶ If relation has index on join attribute, make it inner relation
  - ▶ For each outer tuple, cost of probing inner index is 1.2 for hash index, 2-4 for B+, plus cost to retrieve matching S tuples
  - ▶ **Clustered index** typically single I/O (Alt 2) or no more I/O (Alt 1) (unless many matching S tuples)
  - ▶ **Unclustered index** 1 I/O per matching S tuple



# From class 5/Chap. 8: Clustered Index



- ▶ To build clustered (tree) index, first sort the heap file, leaving some free space on each page for future inserts
- ▶ Overflow pages may be needed for inserts
  - ▶ Hence order of data records is **close to** the sort order
- ▶ This is an **Alternative 2** clustered index. For Alternative 1, the rows are *in* the data entries, so the original index lookup (tree or hash) finds the whole row.
- ▶ Oracle index-organized tables and mysql primary key indexes are Alt 1 clustered.

# Duplicate keys in indexes

---

- ▶ B trees: see Sec. 10.7 Duplicates: two ways to go—
  - ▶ Overflow pages, but not “typical”
  - ▶ Just sequential entries with the same key (we’ll assume this)
- ▶ Extendible Hashing: uses overflow pages (pg. 379)
- ▶ Linear Hashing: uses multiple entries in the main pages.
  - ▶ May involve “extra” overflow pages, since splitting doesn’t help with a long sequence of same-key entries.
- ▶ Shouldn’t use a hash index on a low-cardinality column. B-tree is OK (esp. Alt. 3). (Bitmap index is best.)
- ▶ Cost of access for all dups of one key: calculate number of pages of duplicate index entries



# Example of Index Nested Loops (1 / 2)

---

Example: Reserves JOIN Sailors (natural join on sid)

Case 1: Hash-index (Alternative 2) on *sid* of Sailors

- ▶ Choose Sailors as inner relation
- ▶ Scan Reserves: 100K tuples, 1000 page I/Os
- ▶ For each Reserves tuple
  - ▶ 1.2 I/Os to get data entry in index (see pg. 402, 412)
  - ▶ 1 I/O to get (the exactly one) matching Sailors tuple (primary key)
- ▶ Total: **221,000 I/Os**
  - ▶ unless Sailors, 500 pages, fits in buffer pool along with some/all of Reserves, 1000 pages, then only 1500 I/Os
  - ▶ Dbs3: 24GB in buffer pool = 3M 8KB pages = 6M 4KB pages!
  - ▶ But for textbook queries, assume only hundreds of buffer pages.





# Example of Index Nested Loops (2/2)

---

Example: Reserves JOIN Sailors (natural join on sid)

Case 2: Hash-index (Alternative 1 or 2) on *sid* of Reserves

- ▶ Choose Reserves as inner
- ▶ Scan Sailors: 40K tuples, 500 page I/Os
- ▶ For each Sailors tuple
  - ▶ 1.2 I/Os to find index page with data entries
  - ▶ Assuming uniform distribution, 2.5 matching records per sailor
  - ▶ Cost of retrieving records is nothing further (Alt. 1 clustered) or 1 (Alt. 2 clustered) or 2.5 I/Os (Alt. 2 unclustered)
- ▶ Total: **48,500 I/Os** (clustered, alt. 1) **88,500 I/Os** (clustered, alt. 2) or **148,500 I/Os** (unclustered)
  - ▶ Again assuming the buffer pool can't contain the whole tables



# Executing Joins: Sort-Merge

---

- ▶ Sort R and S on the join column (sid, PK of S)
  - ▶ Then scan them to do a **merge** on join column
- ▶ S is scanned once, each row has unique sid
- ▶ Each R **group** (a certain sid) is scanned once
  - ▶ Here only 2.5 records/group on average
- ▶ **Cost:  $M \log M + N \log N + (M+N)$**  (as we will see later)
  - ▶ Text, pg. 403, estimates cost at 7500 I/Os for this example
  - ▶ So better not to use the index in this case!
  - ▶ Note the tables are roughly the same size, the sweet spot for sort-merge join.



# System R Optimizer

---

- ▶ Developed at IBM starting in the 1970's
  - ▶ Most widely used currently; works well for up to 10 joins
- ▶ **Cost estimation**
  - ▶ Statistics maintained in system catalogs
  - ▶ Used to estimate cost of operations and result sizes
  - ▶ Considers combination of CPU and I/O costs
- ▶ **Query Plan Space**
  - ▶ Only the space of **left-deep plans** is considered
  - ▶ Cartesian products avoided



# Left Deep Trees

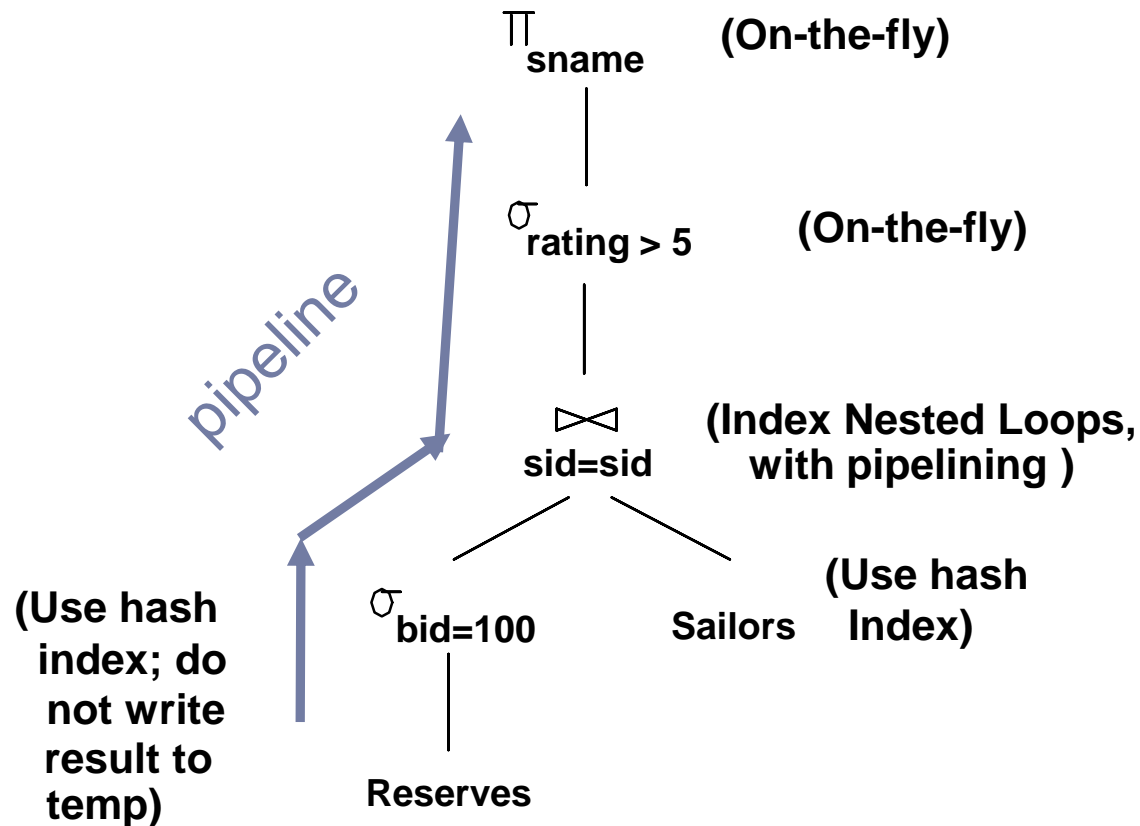
---

- ▶ Consider nested-loop joins
- ▶ Inner tables need to be materialized because they are probed repeatedly for each row of the outer table
  - ▶ Materialized means available as a table, not just a stream of rows, so can be probed by PK index.
- ▶ Left table = outer table
- ▶ Left table can be pipelined: rows used one at a time in order (i.e., doesn't need to be materialized)
- ▶ So Left-deep plans allow output of each operator to be **pipelined** into the next operator without storing it in a temporary relation
- ▶ i.e., Left Deep trees can be “fully pipelined”
- ▶ See pg. 407 for a two-join example



# Example of join with left table pipelined and right table materialized

---



# Cost Estimation

---

For each plan considered, must estimate:

- ▶ Cost of each operator in plan tree
  - ▶ Depends on input cardinalities
  - ▶ Operation and access type: sequential scan, index scan, joins
- ▶ Size of result for each operation in tree
  - ▶ Use information about the input relations
  - ▶ For selections and joins, assume independence of predicates



# Size Estimation and Reduction Factors

---

SELECT attribute list  
FROM relation list  
WHERE  $\text{term}_1$  AND ... AND  $\text{term}_k$

- ▶ Maximum number of tuples is cardinality of cross product
- ▶ **Reduction factor (RF)** associated with each **term** reflects its impact in reducing result size
  - ▶ Implicit assumption that **terms are independent!**
  - ▶  $\text{col} = \text{value}$  has  $\text{RF} = 1/\text{NKeys}(I)$ , given index  $I$  on  $\text{col}$
  - ▶  $\text{col1} = \text{col2}$  has  $\text{RF} = 1/\max(\text{NKeys}(I1), \text{NKeys}(I2))$
  - ▶  $\text{col} > \text{value}$  has  $\text{RF} = (\text{High}(I) - \text{value}) / (\text{High}(I) - \text{Low}(I))$



# Example Schema

---

Sailors (sid: integer, sname: string, rating: integer, age: real)

Reserves (sid: integer, bid: integer, day: dates, rname: string)

- ▶ Similar to old schema; *rname* added
- ▶ Reserves:
  - ▶ 40 bytes long tuple, 100K records, 100 tuples per page, 1000 pages
- ▶ Sailors:
  - ▶ 50 bytes long tuple, 40K tuples, 80 tuples per page, 500 pages



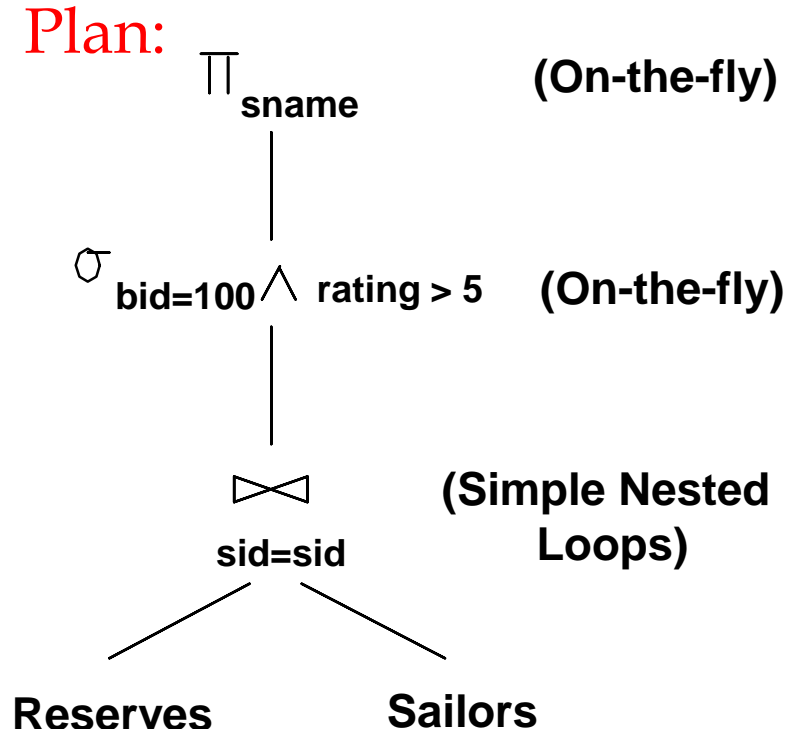


# Evaluation Example

```
SELECT S.sname
FROM Reserves R, Sailors S
WHERE R.sid=S.sid AND
      R.bid=100 AND S.rating>5
```

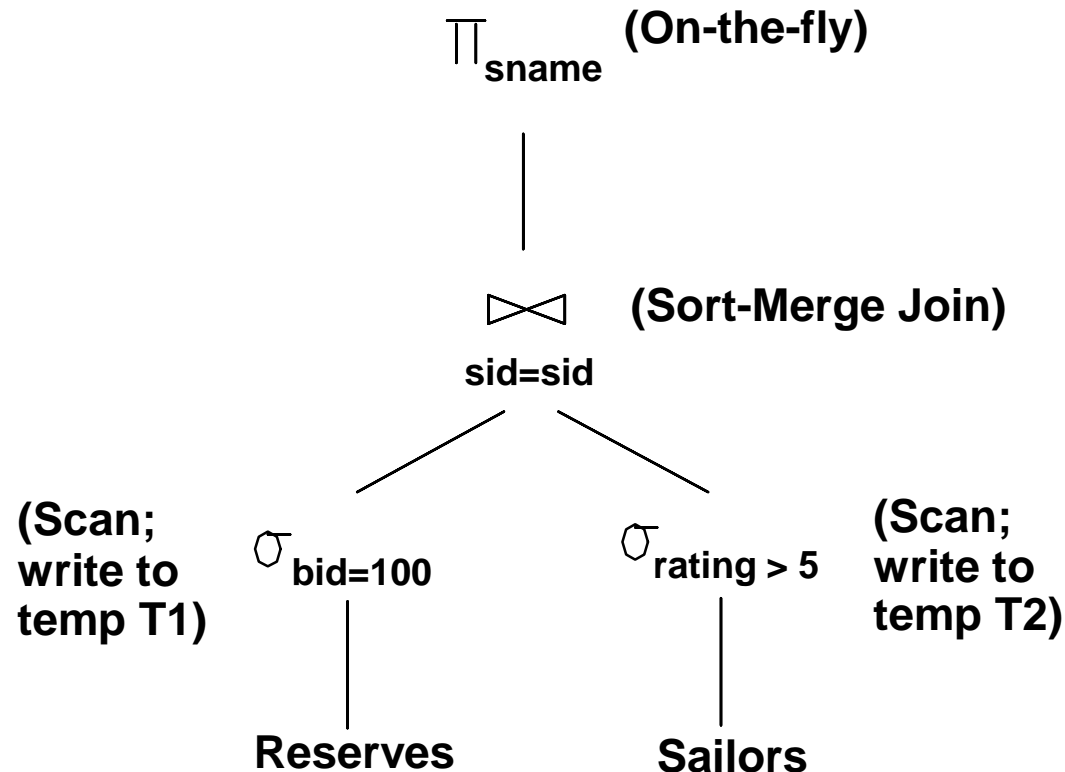
**Cost: 1000+100\*1000\*500 I/Os**

- ▶ R's 1000 pages have 100\*1000 rows each of which causes a scan of S
- ▶ By no means the worst plan!
- ▶ Misses several opportunities:
  - ▶ Selections could have been 'pushed' earlier
  - ▶ No use of any available indexes



# Alternative Plan 1 (No Indexes)

---



# Alternative Plan 1 (No Indexes)

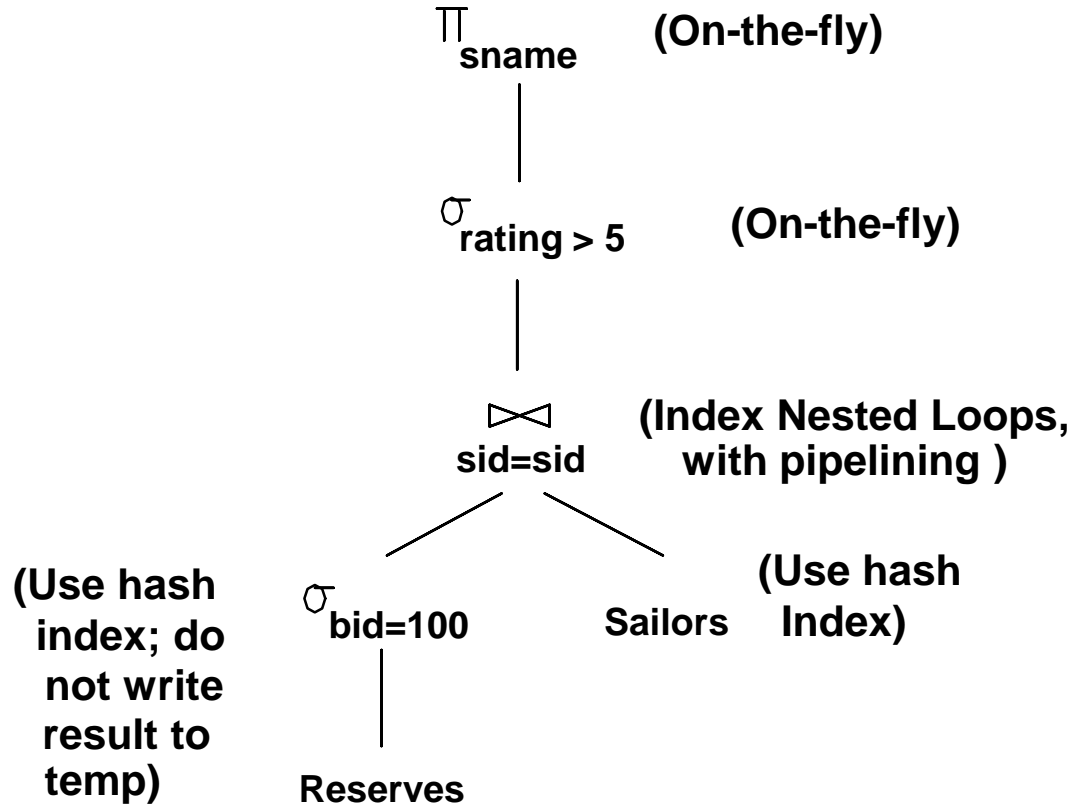
---

- ▶ Main difference: **push down selections**
- ▶ Scan Reserves (1000) + write temp T1 (10 pages, if we have 100 boats, uniform distribution)
- ▶ Scan Sailors (500) + write temp T2 (250 pages, if we have 10 ratings)
- ▶ Sort-merge join T1 and T2
  - ▶ Assume there are 5 buffers:
  - ▶ Sort T1 ( $2 \times 2 \times 10$ ), Sort T2 ( $2 \times 4 \times 250$ ), Merge (10+250)
  - ▶ **Total: 4060 page I/Os**



# Alternative Plan 2 (With Indexes)

---



## Alternative Plan 2 (With Indexes)

---

- ▶ With clustered index on *bid* of Reserves, we get  $100,000/100 = 1000$  tuples on  $1000/100 = 10$  pages
- ▶ Inner Nested Loop join with **pipelining** (result not materialized)
- ▶ Join column *sid* is a key for Sailors
  - ▶ At most one matching tuple, unclustered index on *sid* OK
- ▶ Decision not to push *rating*>5 before the join is based on availability of *sid* index on Sailors
- ▶ **Cost:**
  - ▶ Selection of Reserves tuples 10 I/Os
  - ▶ For each, must get matching Sailors tuple ( $1000 \times 1.2$ )
  - ▶ Total **1210 I/Os**



# Summary

---

- ▶ There are several alternative evaluation algorithms for each relational operator.
- ▶ A query is evaluated by converting it to a tree of operators and evaluating the operators in the tree.
- ▶ Must understand query optimization in order to fully understand the performance impact of a given database design (relations, indexes) on a workload (set of queries).
- ▶ Two parts to optimizing a query:
  - ▶ Consider a set of alternative plans.
    - ▶ Must prune search space; typically, left-deep plans only.
  - ▶ Must estimate cost of each plan that is considered.
    - ▶ Must estimate size of result and cost for each plan node.
- ▶ *Key issues: Statistics, indexes, operator implementations.*