We will cover these parts of the book (8th edition):

2.6 3.1.1-3.1.3 (up to page 207) 3.2.1-3.2.4 3.3.1, 3.3.2



Matrices

A matrix is a rectangular array of numbers.
A matrix with m rows and n columns is called an m×n matrix.

Example:
$$A = \begin{bmatrix} -1 & 1 \\ 2.5 & -0.3 \\ 8 & 0 \end{bmatrix}$$
 is a 3x2 matrix

A matrix with the same number of rows and columns is called square.

Two matrices are equal if they have the same number of rows and columns and the corresponding entries in every position are equal.



Matrices

A general description of an m×n matrix $A = [a_{ii}]$:

 $A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & & \\$ $\begin{bmatrix} a_{i1}, a_{i2}, \dots, a_{in} \end{bmatrix}$ i-th row of A

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Matrix Addition

Let A = [a_{ij}] and B = [b_{ij}] be m×n matrices.
The sum of A and B, denoted by A+B, is the m×n matrix that has a_{ij} + b_{ij} as its (i, j)th element.
In other words, A+B = [a_{ii} + b_{ij}].

Example:

$$\begin{bmatrix} -2 & 1 \\ 4 & 8 \\ -3 & 0 \end{bmatrix} + \begin{bmatrix} 5 & 9 \\ -3 & 6 \\ -4 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 10 \\ 1 & 14 \\ -7 & 1 \end{bmatrix}$$

Let A be an m×k matrix and B be a k×n matrix.
The product of A and B, denoted by AB, is the m×n matrix with (i, j)th entry equal to the sum of the products of the corresponding elements from the i-th row of A and the j-th column of B.

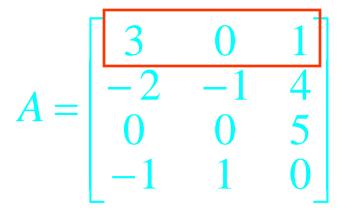
► In other words, if $AB = [c_{ii}]$, then

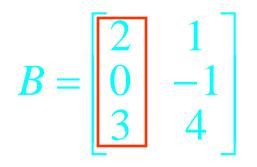
$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{ik}b_{kj} = \sum_{t=1}^{k} a_{it}b_{tj}$$



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► A more intuitive description of calculating C = AB:





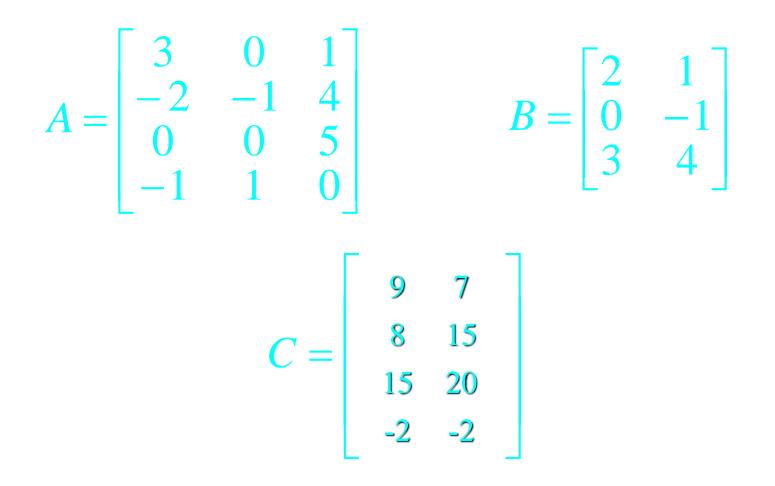
- Take the first column of B
- Turn it counterclockwise by 90 degrees and superimpose it on the first row of A
- Multiply corresponding entries in A and B and add the products: $3x^2 + 0x^0 + 1x^3 = 9$
- Enter the result in the upper-left corner of C



- Now superimpose the first column of B on the second, third, ..., m-th row of A to obtain the entries in the first column of C (same order).
- Then repeat this procedure with the second, third, ..., n-th column of B, to obtain to obtain the remaining columns in C (same order).
- After completing this algorithm, the new matrix C contains the product AB.



• Let us calculate the complete matrix C:



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Identity Matrices

The identity matrix of order n is the n×n matrix $I_n = [\delta_{ij}]$, where $\delta_{ij} = 1$ if i = j and $\delta_{ij} = 0$ if $i \neq j$:

$$A = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ & \ddots & & \ddots & \\ & \ddots & & \ddots & \\ & \ddots & & \ddots & \\ 0 & 0 & \dots & 1 \end{bmatrix}$$

Multiplying an mxn matrix A by an identity matrix of appropriate size does not change this matrix:

$$AI_n = I_m A = A$$



Powers and Transposes of Matrices

The power function can be defined for square matrices. If A is an n×n matrix, we have:

 $A^{0} = I_{n},$ $A^{r} = AAA...A \text{ (r times the letter A)}$

The transpose of an m×n matrix A = [a_{ij}], denoted by A^t, is the n×m matrix obtained by interchanging the rows and columns of A.

► In other words, if $A^t = [b_{ij}]$, then $b_{ij} = a_{ji}$ for i = 1, 2, ..., n and j = 1, 2, ..., m.

Powers and Transposes of Matrices

•Example $A = \begin{bmatrix} 2 & 1 \\ 0 & -1 \\ 3 & 4 \end{bmatrix}$ $A^{t} = \begin{bmatrix} 2 & 0 & 3 \\ 1 & -1 & 4 \end{bmatrix}$

A square matrix A is called symmetric if $A = A^t$. Thus $A = [a_{ij}]$ is symmetric if $a_{ij} = a_{ji}$ for all i = 1, 2, ..., n and j = 1, 2, ..., n.

$$A = \begin{bmatrix} 5 & 1 & 3 \\ 1 & 2 & -9 \\ 3 & -9 & 4 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & 3 & 1 \\ 1 & 3 & 1 \\ 1 & 3 & 1 \end{bmatrix}$$

A is symmetric, B is not.

A matrix with entries that are either 0 or 1 is called a zero-one matrix. Zero-one matrices are often used like a "table" to represent discrete structures.

► We can define Boolean operations on the entries in zero-one matrices:

а	b	a∨p
0	0	0
0	1	0
1	0	0
1	1	1

a	d	a∨p
0	0	0
0	1	1
1	0	1
1	1	1



• Let $A = [a_{ij}]$ and $B = [b_{ij}]$ be m×n zero-one matrices.

Then the join of A and B is the zero-one matrix with (i, j)th entry $a_{ij} \lor b_{ij}$. The join of A and B is denoted by $A \lor B$.

The meet of A and B is the zero-one matrix with (i, j)th entry $a_{ij} \wedge b_{ij}$. The meet of A and B is denoted by $A \wedge B$.



• Example:

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix}$$
 $B = \begin{bmatrix} 0 & 1 \\ 1 & 1 \\ 0 & 0 \end{bmatrix}$

 Join:
 $A \lor B = \begin{bmatrix} 1 \lor 0 & 1 \lor 1 \\ 0 \lor 1 & 1 \lor 1 \\ 1 \lor 0 & 0 \lor 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 0 \end{bmatrix}$

 Meet:
 $A \land B = \begin{bmatrix} 1 \land 0 & 1 \land 1 \\ 0 \land 1 & 1 \land 1 \\ 1 \land 0 & 0 \land 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$

- Let $A = [a_{ij}]$ be an m×k zero-one matrix and $B = [b_{ij}]$ be a k×n zero-one matrix.
- ►Then the Boolean product of A and B, denoted by AoB, is the m×n matrix with (i, j)th entry [c_{ii}], where

$$\mathbf{E}_{ij} = (\mathbf{a}_{i1} \land \mathbf{b}_{1j}) \lor (\mathbf{a}_{i2} \land \mathbf{b}_{2i}) \lor \ldots \lor (\mathbf{a}_{ik} \land \mathbf{b}_{kj}).$$

Note that the actual Boolean product symbol has a dot in its center.

► Basically, Boolean multiplication works like the multiplication of matrices, but with computing ∧ instead of the product and ∨ instead of the sum.



Example:

$$A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \qquad B = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

 $A \circ B = \begin{bmatrix} (1 \land 0) \lor (0 \land 0) & (1 \land 1) \lor (0 \land 1) \\ (1 \land 0) \lor (1 \land 0) & (1 \land 1) \lor (1 \land 1) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$



Let A be a square zero-one matrix and r be a positive integer.

The r-th Boolean power of A is the Boolean product of r factors of A. The r-th Boolean power of A is denoted by A^[r].

 $A^{[0]} = I_n,$ $A^{[r]} = AoAo...oA \quad (r \text{ times the letter } A)$



Algorithms

Algorithms

What is an algorithm?

► An algorithm is a finite set of precise instructions for performing a computation or for solving a problem.

This is a rather vague definition. You will get to know a more precise and mathematically useful definition when you attend CS420 or CS620.

▶ But this one is good enough for now...

Algorithms

- Properties of algorithms:
- Input from a specified set,
- **Output** from a specified set (solution),
- **Definiteness** of every step in the computation,
- Correctness of output for every possible input,
- Finiteness of the number of calculation steps,
- Effectiveness of each calculation step and
- Generality for a class of problems.

We will use a pseudocode to specify algorithms, which slightly reminds us of Basic and Pascal.

Example: an algorithm that finds the maximum element in a finite sequence

- ▶procedure max(a₁, a₂, ..., a_n: integers)
- ▶max := a₁
- **▶ for** i := 2 **to** n
- if max < a_i then max := a_i
- Return max{max is the largest element}

Another example: a linear search algorithm, that is, an algorithm that linearly searches a sequence for a particular element.

procedure linear_search(x: integer; a₁, a₂, ..., a_n: integers)

- **▶i** := 1
- while (i \leq n and x \neq a_i)
- ▶ i := i + 1
- ▶ if i ≤ n then location := i
- ►else location := 0

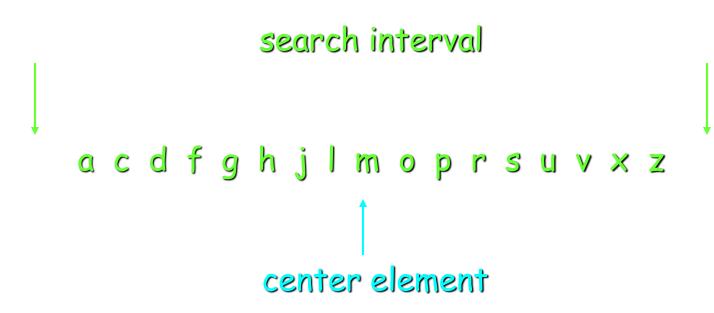
Return location {location is the subscript of the term that equals x, or is zero if x is not found}

► If the terms in a sequence are ordered, a binary search algorithm is more efficient than linear search.

The binary search algorithm iteratively restricts the relevant search interval until it closes in on the position of the element to be located.

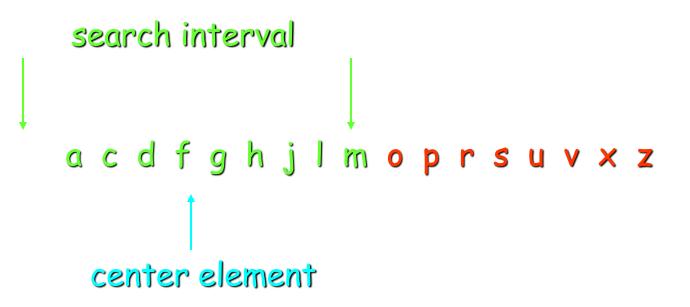


binary search for the letter 'j'



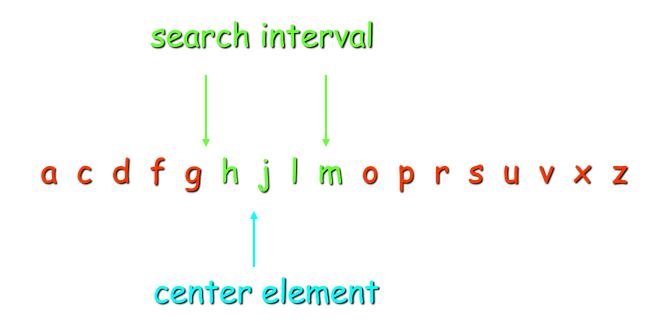


binary search for the letter 'j'

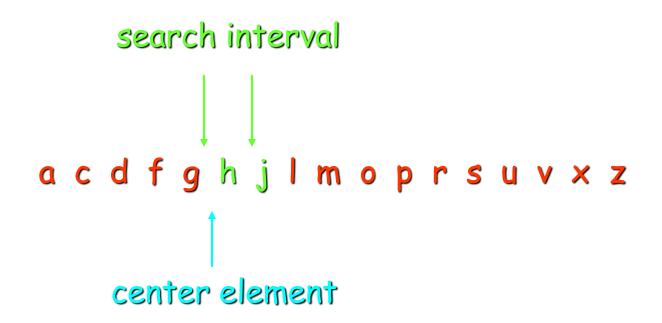


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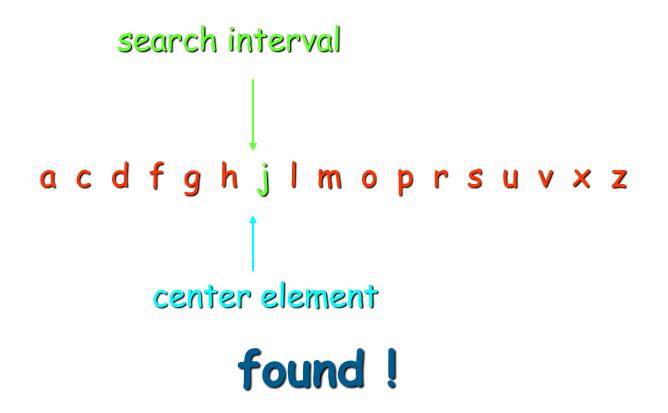














- procedure binary_search(x: integer; a₁, a₂, ..., a_n: integers)
- i := 1 {i is left endpoint of search interval}
 i := n {i is right endpoint of search interval}
- **while** (i < j)

▶ begin

- $m := \lfloor (i + j)/2 \rfloor$
- if x > a_m then i := m + 1
- ▶ **else** j := m

▶ end

- ► if x = a_i then location := i
- ►else location := 0

Return location {location is the subscript of the term that equals x, or is zero if x is not found}

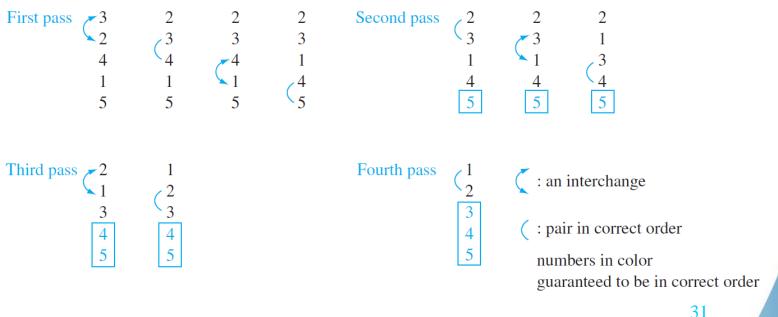


▶ procedure bubblesort(a₁, a₂, ..., a_n: real numbers, n≥ 2)
▶ for i := 1 to n-1
▶ for j := 1 to n-1
▶ if a_j > a_{j+1} then interchange a_j and a_{j+1}
▶ {a₁, a₂, ..., a_n is in increasing order}



► Bubble sort:

It puts a list into increasing order by successively comparing adjacent elements, interchanging them if they are in the wrong order. To carry out the bubble sort, we perform the basic operation, that is, interchanging a larger element with a smaller one following it, starting at the beginning of the list, for a full pass. We iterate this procedure until the sort is complete.





The growth of functions is usually described using the big-O notation.

Definition: Let f and g be functions from the integers or the real numbers to the real numbers.
We say that f(x) is O(g(x)) if there are constants C and k such that

- $\bullet |f(x)| \leq C|g(x)|$
- whenever x > k.

► This is read as "f(x) is big-oh of g(x)"



►When we analyze the growth of complexity functions, f(x) and g(x) are always positive.

- Therefore, we can simplify the big-O requirement to
- $f(x) \le C \cdot g(x)$ whenever x > k.

• If we want to show that f(x) is O(g(x)), we only need to find one pair (C, k) (which is never unique).



The idea behind the big-O notation is to establish an upper boundary for the growth of a function f(x) for large x.

- ► This boundary is specified by a function g(x) that is usually much simpler than f(x).
- •We accept the constant C in the requirement
- $f(x) \le C \cdot g(x)$ whenever x > k,
- because C does not grow with x.

•We are only interested in large x, so it is OK if $f(x) > C \cdot g(x)$ for $x \le k$.



- Example:
- Show that $f(x) = x^2 + 2x + 1$ is $O(x^2)$.
- For x > 1 we have:
- $x^2 + 2x + 1 \le x^2 + 2x^2 + x^2$ $x^2 + 2x + 1 \le 4x^2$
- Therefore, for C = 4 and k = 1:
- $f(x) \le Cx^2$ whenever x > k.
- ► \Rightarrow f(x) is O(x²).

• Question: If f(x) is $O(x^2)$, is it also $O(x^3)$?

► Yes. x³ grows faster than x², so x³ grows also faster than f(x).

► Therefore, we always have to find the smallest simple function g(x) for which f(x) is O(g(x)).

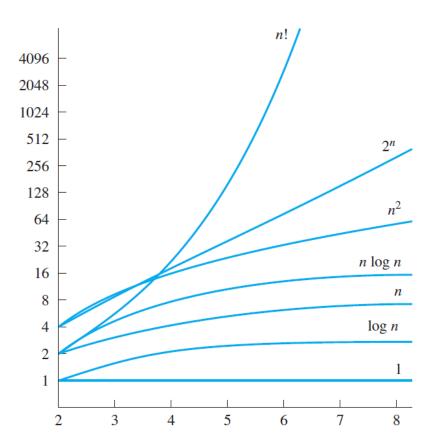
• Let $f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$, where $a_0, a_1, \dots, a_{n-1}, a_n$ are real numbers. Then f(x) is $O(x^n)$



The Growth of Functions

"Popular" functions g(n) are
n log n, 1, 2ⁿ, n², n!, n, n³, log n

- Listed from slowest to fastest growth:
- 1
- log n
- n
- n log n
- n²
- n³
- 2ⁿ
- n!



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The Growth of Combinations of Functions

Suppose that $f_1(x)$ is $O(g_1(x))$ and that $f_2(x)$ is $O(g_2(x))$. Then $(f_1+f_2)(x)$ is O(g(x)), where $g(x) = (\max(|g_1(x)|, |g_2(x)|))$ for all x.

Suppose that $f_1(x)$ is $O(g_1(x))$ and that $f_2(x)$ is $O(g_2(x))$. Then $(f_1f_2)(x)$ is $O(g_1(x)g_2(x))$.



Complexity of Algorithms

Obviously, on sorted sequences, binary search is more efficient than linear search.

How can we analyze the efficiency of algorithms?

- •We can measure the
- time (number of elementary computations) and
- space (number of memory cells) that the algorithm requires.

These measures are called time complexity and space complexity, respectively.



Time Complexity

- The time complexity of an algorithm can be expressed in terms of the number of operations used by the algorithm when the input has a particular size.
- Time complexity is described in terms of the number of operations required instead of actual computer time because of the difference in time needed for different computers to perform basic operations.

Time Complexity

What is the time complexity of the linear search algorithm?

► We will determine the **worst-case** number of comparisons as a function of the number n of terms in the sequence.

By the worst-case performance of an algorithm, we mean the largest number of operations needed to solve the given problem.

► The worst case for the linear algorithm occurs when the element to be located is not included in the sequence.

In that case, every item in the sequence is compared to the element to be located.



Algorithm Examples

Here is the linear search algorithm again:
 procedure linear_search(x: integer; a₁, a₂, ..., a_n: integers)

≻i := 1

- while (i \leq n and x \neq a_i)
- ▶ i := i + 1
- **if** $i \le n$ **then** location := i
- ►else location := 0

Return location {location is the subscript of the term that equals x, or is zero if x is not found}

► For n elements, the loop

- while (i ≤ n and x ≠ a_i)
 i := i + 1
- ▶ is processed n times, requiring 2n comparisons.
- When it is entered for the (n+1)th time, only the comparison i \leq n is executed and terminates the loop.
- Finally, the comparison
- if $i \le n$ then location := i

is executed, so all in all we have a worst-case time complexity of 2n + 2.



Reminder: Binary Search Algorithm

procedure binary_search(x: integer; a₁, a₂, ..., a_n: integers)

- i := 1 {i is left endpoint of search interval}
- >j := n {j is right endpoint of search interval}
 >while (i < j)</pre>

▶ begin

- $m := \lfloor (i + j)/2 \rfloor$
- if x > a_m then i := m + 1
- ▶ **else** j := m

▶ end

- ► if x = a_i then location := i
- ►else location := 0

Return location {location is the subscript of the term that equals x, or is zero if x is not found}



What is the time complexity of the binary search algorithm?

Again, we will determine the worst-case number of comparisons as a function of the number n of terms in the sequence.

• Let us assume there are $n = 2^k$ elements in the list, which means that $k = \log n$.

If n is not a power of 2, it can be considered part of larger list, where 2^k < n < 2^{k+1}.



- In the first cycle of the loop
- ► while (i < j)</p>
- ▶ begin
- $m := \lfloor (i + j)/2 \rfloor$
- if x > a_m then i := m + 1
- ▶ **else** j := m

►end

► the search interval is restricted to 2^{k-1} elements, using two comparisons.



► In the second cycle, the search interval is restricted to 2^{k-2} elements, again using two comparisons.

► This is repeated until there is only one (2⁰) element left in the search interval.

• At this point 2k comparisons have been conducted.



- Then, the comparison
- ► while (i < j)</p>
- exits the loop, and a final comparison
- ► if x = a_i then location := i
- determines whether the element was found.

• Therefore, the overall time complexity of the binary search algorithm is $2k + 2 = 2 \lceil \log n \rceil + 2$.

In general, we are not so much interested in the time and space complexity for small inputs.

► For example, while the difference in time complexity between linear and binary search is meaningless for a sequence with n = 10, it is gigantic for $n = 2^{30}$.

For example, let us assume two algorithms A and B that solve the same class of problems.

The time complexity of A is 5,000n, the one for B is 1.1^n for an input with n elements.

Comparison: time complexity of algorithms A and B

Input Size	Algorithm A	Algorithm B
n	5,000n	[1.1 ⁿ]
10	50,000	3
100	500,000	13,781
1,000	5,000,000	2.5x10 ⁴¹
1,000,000	5x10 ⁹	4.8x10 ⁴¹³⁹²



This means that algorithm B cannot be used for large inputs, while running algorithm A is still feasible.

► So what is important is the **growth** of the complexity functions.

 The growth of time and space complexity with increasing input size n is a suitable measure for the comparison of algorithms.

The Growth of Functions

► A problem that can be solved with polynomial worstcase complexity is called tractable.

Problems of higher complexity are called intractable.

Problems that no algorithm can solve are called unsolvable.

► You will find out more about this in CS420.



Complexity Examples

- What does the following algorithm compute?
- >procedure who_knows(a₁, a₂, ..., a_n: integers)
 >who_knows := 0
- **▶ for** i := 1 to n-1
- for j := i+1 to n
- if $|a_i a_j|$ > who_knows then who_knows := $|a_i - a_j|$
- •{who_knows is the maximum difference between any two numbers in the input sequence}
- ▶ Comparisons: n-1 + n-2 + n-3 + ... + 1

$$= (n - 1)n/2 = 0.5n^2 - 0.5n$$

► Time complexity is O(n²).

Complexity Examples

- Another algorithm solving the same problem:
- procedure max_diff($a_1, a_2, ..., a_n$: integers)
- ►min := a₁
- ▶max := a₁
- **▶ for** i := 2 to n
- if a_i < min then min := a_i
- else if a_i > max then max := a_i
 max_diff := max min
- Comparisons (worst case): 2n 2
- ► Time complexity is O(n).