We will cover these parts of the book (8th edition):

9.4.1-9.4.4 9.5 9.6.1 10.1 10.2.1-10.2.4 10.2.7



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- What is the **closure** of a relation?
- Definition: Let R be a relation on a set A. R may or may not have some property P, such as reflexivity, symmetry, or transitivity.
- If there is a relation S that contains R and has property P, and S is a subset of every subset of $A \times A$ relation that contains R and has property P, then S is called the **closure** of R with respect to P.

Note that the closure of a relation with respect to a property may not exist.



Example I: Find the reflexive closure of relation R
= {(1, 1), (1, 2), (2, 1), (3, 2)} on the set A = {1, 2, 3}.

Solution: We know that any reflexive relation on A must contain the elements (1, 1), (2, 2), and (3, 3).
By adding (2, 2) and (3, 3) to R, we obtain the reflexive relation S, which is given by S = {(1, 1), (1, 2), (2, 1), (2, 2), (3, 2), (3, 3)}.

►S is reflexive, contains R, and is contained within every reflexive relation that contains R.

► Therefore, S is the **reflexive closure** of R.



Example II: Find the symmetric closure of the relation R = {(a, b) | a > b} on the set of positive integers.

Solution: The symmetric closure of R is given by
R∪R⁻¹ = {(a, b) | a > b} ∪ {(b, a) | a > b}
= {(a, b) | a ≠ b}



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• Example III: Find the transitive closure of the relation $R = \{(1, 3), (1, 4), (2, 1), (3, 2)\}$ on the set $A = \{1, 2, 3, 4\}$.

Solution: R would be transitive, if for all pairs
 (a, b) and (b, c) in R there were also a pair (a, c) in R.

If we add the missing pairs (1, 2), (2, 3), (2, 4), and (3, 1), will R be transitive?

No, because the extended relation R contains (3, 1) and (1, 4), but does not contain (3, 4), (1, 1), (2, 2), (3, 3).

► By adding new elements to R, we also add new requirements for its transitivity. We need to look at paths in digraphs to solve this problem. 5



Imagine that we have a relation R that represents all train connections in the US.

► For example, if (Boston, Philadelphia) is in R, then there is a **direct** train connection from Boston to Philadelphia.

If R contains (Boston, Philadelphia) and (Philadelphia, Washington), there is an indirect connection from Boston to Washington.

 Because there are indirect connections, it is not possible by just looking at R to determine which cities are connected by trains.

The transitive closure of R contains exactly those pairs of cities that are connected, either directly or indirectly.



Definition: A path from a to b in the directed graph G is a sequence of one or more edges (x₀, x₁), (x₁, x₂), (x₂, x₃), ..., (x_{n-1}, x_n) in G, where x₀ = a and x_n = b.
In other words, a path is a sequence of edges where the terminal vertex of an edge is the same as the initial vertex of the next edge in the path.

This path is denoted by $x_0, x_1, x_2, ..., x_n$ and has length n.

► A path that begins and ends at the same vertex is called a circuit or cycle.



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Example: Let us take a look at the following graph:



Is c,a,b,d,b a path in this graph?YesIs d,b,b,b,d,b,d a circuit in this graph?YesIs there any circuit including c in this graph?No

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Due to the one-to-one correspondence between graphs and relations, we can transfer the definition of path from graphs to relations:

▶ Definition: There is a path from a to b in a relation R, if there is a sequence of elements a, $x_1, x_2, ..., x_{n-1}$, b with $(a, x_1) \in R$, $(x_1, x_2) \in R$, ..., and $(x_{n-1}, b) \in R$.

▶ Theorem: Let R be a relation on a set A. There is a path from a to b if and only if $(a, b) \in R^n$ for some positive integer n.



According to the train example, the transitive closure of a relation consists of the pairs of vertices in the associated directed graph that are connected by a path.

Definition: Let R be a relation on a set A. The connectivity relation R* consists of the pairs (a, b) such that there is a path between a and b in R.

► We know that Rⁿ consists of the pairs (a, b) such that a and b are connected by a path of length n.

Therefore, R* is the union of Rⁿ across all positive integers n:

$$R^* = \sum_{n=1}^{\infty} R^n = R^1 \cup R^2 \cup R^3 \cup \dots$$



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► Theorem: The transitive closure of a relation R equals the connectivity relation R*.

▶ But how can we compute R* ?

Lemma: Let A be a set with n elements, and let R be a relation on A. If there is a path in R from a to b, then there is such a path with length not exceeding n.

• Moreover, if a \neq b and there is a path in R from a to b, then there is such a path with length not exceeding (n – 1).



This lemma is based on the observation that if a path from a to b visits any vertex more than once, it must include at least one circuit.

These circuits can be eliminated from the path, and the reduced path will still connect a and b.

- ► **Theorem:** For a relation R on a set A with n elements, the transitive closure R* is given by: ► $R^* = R \cup R^2 \cup R^3 \cup ... \cup R^n$
- For matrices representing relations we have:
- $\bullet \mathsf{M}_{\mathsf{R}^*} = \mathsf{M}_{\mathsf{R}} \lor \mathsf{M}_{\mathsf{R}}^{[2]} \lor \mathsf{M}_{\mathsf{R}}^{[3]} \lor \ldots \lor \mathsf{M}_{\mathsf{R}}^{[n]}$



Let us finally solve Example III by finding the transitive closure of the relation R = {(1, 3), (1, 4), (2, 1), (3, 2)} on the set A = {1, 2, 3, 4}.

► R can be represented by the following matrix M_R:

$$M_R = \begin{bmatrix} 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

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$$M_R^{[2]} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$M_R^{[4]} = \begin{bmatrix} 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$





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Solution: The transitive closure of the relation $R = \{(1, 3), (1, 4), (2, 1), (3, 2)\}$ on the set $A = \{1, 2, 3, 4\}$ is given by the relation

 $\{(1, 1), (1, 2), (1, 3), (1, 4), (2, 1), (2, 2), (2, 3), (2, 4), (3, 1), (3, 2), (3, 3), (3, 4)\}$



Equivalence Relations

Equivalence relations are used to relate objects that are similar in some way.

Definition: A relation on a set A is called an equivalence relation if it is reflexive, symmetric, and transitive.

► Two elements that are related by an equivalence relation R are called equivalent.

The notation $a \sim b$ is often used to denote that a and b are equivalent.



Equivalence Relations

Since R is symmetric, a is equivalent to b whenever b is equivalent to a.

► Since R is reflexive, every element is equivalent to itself.

Since R is transitive, if a and b are equivalent and b and c are equivalent, then a and c are equivalent.

Obviously, these three properties are necessary for a reasonable definition of equivalence.



Equivalence Relations

• **Example:** Suppose that R is the relation on the set of strings that consist of English letters such that aRb if and only if I(a) = I(b), where I(x) is the length of the string x. Is R an equivalence relation?

- Solution:
- R is reflexive, because I(a) = I(a) and therefore aRa for any string a.
- R is symmetric, because if l(a) = l(b) then l(b) = l(a), so if aRb then bRa.
- R is transitive, because if l(a) = l(b) and l(b) = l(c), then l(a) = l(c), so aRb and bRc implies aRc.
- ▶ R is an equivalence relation.

Definition: Let R be an equivalence relation on a set A. The set of all elements that are related to an element a of A is called the equivalence class of a.

► The equivalence class of a with respect to R is denoted by [a]_R.

When only one relation is under consideration, we will delete the subscript R and write [a] for this equivalence class.

• If $b \in [a]_R$, b is called a representative of this equivalence class.



Example: In the previous example (strings of identical length), what is the equivalence class of the word mouse, denoted by [mouse] ?

Solution: [mouse] is the set of all English words containing five letters.

► For example, 'horse' would be a representative of this equivalence class.



- Theorem: Let R be an equivalence relation on a set
- A. The following statements are equivalent:
- (i) aRb
- (ii) [a] = [b]
- (iii) [a] \cap [b] $\neq \emptyset$

▶ Reminder: A partition of a set S is a collection of disjoint nonempty subsets of S that have S as their union. In other words, the collection of subsets A_i , $i \in I$, forms a partition of S if and only if (i) $A_i \neq \emptyset$ for $i \in I$

- (ii) $A_i \cap A_j = \emptyset$, if $i \neq j$
- (iii) $\cup_{i \in I} A_i = S$



Theorem: Let R be an equivalence relation on a set S. Then the equivalence classes of R form a partition of S. Conversely, given a partition
{A_i | i∈I} of the set S, there is an equivalence relation R that has the sets A_i, i∈I, as its equivalence classes.

Example: Let us assume that Frank, Suzanne and George live in Boston, Stephanie and Max live in Lübeck, and Jennifer lives in Sydney.

Let R be the equivalence relation {(a, b) | a and b live in the same city} on the set P = {Frank, Suzanne, George, Stephanie, Max, Jennifer}.

Then R = {(Frank, Frank), (Frank, Suzanne), (Frank, George), (Suzanne, Frank), (Suzanne, Suzanne), (Suzanne, George), (George, Frank), (George, Suzanne), (George, George), (Stephanie, Stephanie), (Stephanie, Max), (Max, Stephanie), (Max, Max), (Jennifer, Jennifer)}.

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- Then the equivalence classes of R are:
- {{Frank, Suzanne, George}, {Stephanie, Max}, {Jennifer}}.
- This is a partition of P.

 The equivalence classes of any equivalence relation R defined on a set S constitute a partition of S, because every element in S is assigned to exactly one of the equivalence classes.

- Another example: Let R be the relation $\{(a, b) \mid a \equiv b \pmod{3}\}$ on the set of integers.
- ► Is R an equivalence relation?
- ► Yes, R is reflexive, symmetric, and transitive.
- What are the equivalence classes of R ?

► Again, these three classes form a partition of the set of integers.



Sometimes, relations define an order on the elements in a set.

Definition: A relation R on a set S is called a partial ordering or partial order if it is reflexive, antisymmetric, and transitive.

A set S together with a partial ordering R is called a partially ordered set, or poset, and is denoted by (S, R). Members of S are called elements of the poset.

► **Example:** Consider the "greater than or equal" relation \ge (defined by {(a, b) | a \ge b}).

- Is \geq a partial ordering on the set of integers?
- \geq is **reflexive**, because a \geq a for every integer a.
- \geq is antisymmetric, because if a \neq b, then a \geq b \wedge b \geq a is false.
- ≥ is transitive, because if a ≥ b and b ≥ c, then a ≥ c.

• Consequently, (Z, \ge) is a partially ordered set.



► Another example: Is the "inclusion relation" a partial ordering on the power set of a set S?

- \subseteq is **reflexive**, because A \subseteq A for every set A.
- \subseteq is antisymmetric, because if A \neq B, then A \subseteq B \land B \subseteq A is false.
- \subseteq is transitive, because if A \subseteq B and B \subseteq C, then A \subseteq C.

• Consequently, $(P(S), \subseteq)$ is a partially ordered set.



- In a poset the notation $a \le b$ denotes that $(a, b) \in R$.
- Note that the symbol ≤ is used to denote the relation in any poset, not just the "less than or equal" relation.
- The notation a < b denotes that $a \le b$, but $a \ne b$.
- If a < b we say "a is less than b" or "b is greater than a".

For two elements a and b of a poset (S, \leq) it is possible that neither a \leq b nor b \leq a.

► Example: In (P(Z), \subseteq), {1, 2} is not related to {1, 3}, and vice versa, since neither is contained within the other.

▶ Definition: The elements a and b of a poset (S, \leq) are called comparable if either a \leq b or b \leq a. When a and b are elements of S such that neither a \leq b nor b \leq a, then a and b are called incomparable.



► For some applications, we require **all** elements of a set to be comparable.

For example, if we want to write a dictionary, we need to define an order on all English words (alphabetic order).

► Definition: If (S, ≤) is a poset and every two elements of S are comparable, S is called a totally ordered or linearly ordered set, and ≤ is called a total order or linear order. A totally ordered set is also called a chain.



- **Example I:** Is (Z, \leq) a totally ordered set?
- Yes, because $a \le b$ or $b \le a$ for all integers a and b.

Example II: Is (Z⁺, |) a totally ordered set?
No, because it contains incomparable elements such as 5 and 7.



• Definition: (S, \leq) is a well-ordered set if it is a poset such that \leq is a total ordering and every nonempty subset of S has a least element.

► **Example I:** The set of ordered pairs of positive integers $(Z^+ \times Z^+)$, with $(a_1, a_2) \le (b_1, b_2)$ if $a_1 < b_1$, or if $a_1 = b_1$ and $a_2 \le b_2$ (the lexicographic ordering) is a well-ordered set. Because it is a total ordering and (1,1) is the least element.

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The Principle of Well-ordered Induction:

- Suppose that S is a well-ordered set. Then P(x) is true for all $x \in S$, if
 - ► Inductive step: For every $y \in S$, if P(x) is true for all $x \in S$ with x < y, then P(y) is true.

▶ **Proof:** Suppose it is not the case that P(x) is true for all $x \in S$. Then there is an element $y \in S$ such that P(y) is false. Consequently, the set $A = \{x \in S \mid P(x) \text{ is false}\}$ is nonempty.



▶ Because S is well-ordered, A has a least element a. By the choice of a as a least element of A, we know that P(x) is true for all $x \in S$ with x < a. This implies by the inductive step P(a) is true. This contradiction shows that P(x) must be true for all $x \in S$.



Let us switch to a new topic:

Graphs

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Definition: A simple graph G = (V, E) consists of V, a nonempty set of vertices (or nodes), and E, a set of unordered pairs of distinct elements of V called edges. Each edge has either one or two vertices associated with it, called its endpoints. An edge is said to connect its endpoints.

► A simple graph is just like a directed graph, but with no specified direction of its edges.

Sometimes we want to model multiple connections between vertices, which is impossible using simple graphs.

In these cases, we have to use multigraphs.



▶ Definition: A multigraph G = (V, E) consists of a set V of vertices, a set E of edges, and a function f from E to {{u, v} | u, v ∈ V, u ≠ v}.

► The edges e_1 and e_2 are called **multiple or parallel** edges if $f(e_1) = f(e_2)$.

Note:

- Edges in multigraphs are not necessarily defined as pairs, but can be of any type.
- No loops are allowed in multigraphs ($u \neq v$).



• Example: A multigraph G with vertices V = $\{a, b, c, d\}$, edges $\{1, 2, 3, 4, 5\}$ and function f with $f(1) = \{a, b\}$, $f(2) = \{a, b\}$, $f(3) = \{b, c\}$, $f(4) = \{c, d\}$ and $f(5) = \{c, d\}$:



If we want to define loops, we need the following type of graph:

▶ Definition: A pseudograph G = (V, E) consists of a set V of vertices, a set E of edges, and a function f from E to {{u, v} | u, v ∈ V}.

An edge e is a loop if $f(e) = \{u, u\}$ for some $u \in V$.



Here is a type of graph that we already know:

- Definition: A directed graph G = (V, E) consists of a set V of vertices and a set E of edges that are ordered pairs of elements in V.
- Ieading to a new type of graph:
- ▶ Definition: A directed multigraph G = (V, E)consists of a set V of vertices, a set E of edges, and a function f from E to {(u, v) | u, v ∈ V}.
- The edges e_1 and e_2 are called **multiple edges** if $f(e_1) = f(e_2)$.



► **Example:** A directed multigraph G with vertices $V = \{a, b, c, d\}$, edges $\{1, 2, 3, 4, 5\}$ and function f with f(1) = (a, b), f(2) = (b, a), f(3) = (c, b), f(4) = (c, d) and f(5) = (c, d):



Types of Graphs and Their Properties

Туре	Edges	Multiple Edges?	Loops?
simple graph	undirected	no	no
multigraph	undirected	yes	no
pseudograph	undirected	yes	yes
simple dir. graph	directed	no	no
dir. multigraph	directed	yes	yes
mixed graph	dir and und	lir yes	yes



Graph Models

Example I: How can we represent a network of (bidirectional) railways connecting a set of cities?

We should use a simple graph with an edge {a, b} indicating a direct train connection between cities a and b.



Graph Models

Example II: In a round-robin tournament, each team plays against each other team exactly once. How can we represent the results of the tournament (which team beats which other team)?

We should use a directed graph with an edge (a, b) indicating that team a beats team b.



Definition: Two vertices u and v in an undirected graph G are called adjacent (or neighbors) in G if {u, v} is an edge in G.

If e = {u, v}, the edge e is called incident with the vertices u and v. The edge e is also said to connect u and v.

The vertices u and v are called endpoints of the edge {u, v}.



Definition: The set of all neighbors of a vertex v of G = (V, E), denoted by N(v), is called the neighborhood of v.

► If A is a subset of V, we denote by N(A) the set of all vertices in G that are adjacent to at least one vertex in A. So, N(A) = $Uv \in A N(v)$.

• **Definition:** The **degree** of a vertex in an undirected graph is the number of edges incident with it, except that a loop at a vertex contributes twice to the degree of that vertex.

In other words, you can determine the degree of a vertex in a displayed graph by counting the lines that touch it.

► The degree of the vertex v is denoted by deg(v).



► A vertex of degree 0 is called **isolated**, since it is not adjacent to any vertex.

Note: A vertex with a loop at it has at least degree 2 and, by definition, is not isolated, even if it is not adjacent to any other vertex.

A vertex of degree 1 is called pendant. It is adjacent to exactly one other vertex.



Example: Which vertices in the following graph are isolated, which are pendant, and what is the maximum degree? What type of graph is it?



Solution: Vertex f is isolated, and vertices a, d and j are pendant. The maximum degree is deg(g) = 5. This graph is a pseudograph (undirected, loops).

Let us look at the same graph again and determine the number of its edges and the sum of the degrees of all its vertices:



Result: There are 9 edges, and the sum of all degrees is 18. This is easy to explain: Each new edge increases the sum of degrees by exactly two.



The Handshaking Theorem: Let G = (V, E) be an undirected graph with e edges. Then

► $2e = \sum_{v \in V} deg(v)$

Note: This theorem holds even if multiple edges and/or loops are present.

Example: How many edges are there in a graph with 10 vertices, each of degree 6?

Solution: The sum of the degrees of the vertices is 6.10 = 60. According to the Handshaking Theorem, it follows that 2e = 60, so there are 30 edges.

Graph Theorems

Theorem: An undirected graph has an even number of vertices of odd degree.

Idea: There are three possibilities for adding an edge to connect two vertices in the graph:



Both vertices have even degree



Both vertices have odd degree



One vertex has odd degree, the other even

After:

Both vertices have odd degree

Both vertices have even degree

One vertex has even degree, the other odd



Graph Theorems

There are two possibilities for adding a loop to a vertex in the graph:

Before:

The vertex has even degree





After:

The vertex has even degree

The vertex has odd degree



 So if there is an even number of vertices of odd degree in the graph, it will still be even after adding an edge.

Therefore, since an undirected graph with no edges has an even number of vertices with odd degree (zero), the same must be true for any undirected graph.



Definition: When (u, v) is an edge of the graph G with directed edges, u is said to be adjacent to v, and v is said to be adjacent from u.

The vertex u is called the initial vertex of (u, v), and v is called the terminal vertex of (u, v).

The initial vertex and terminal vertex of a loop are the same.

Definition: In a graph with directed edges, the indegree of a vertex v, denoted by deg⁻(v), is the number of edges with v as their terminal vertex.

► The out-degree of v, denoted by deg⁺(v), is the number of edges with v as their initial vertex.

Question: How does adding a loop to a vertex change the in-degree and out-degree of that vertex?

Answer: It increases both the in-degree and the out-degree by one.



Example: What are the in-degrees and outdegrees of the vertices a, b, c, d in this graph:





► **Theorem:** Let G = (V, E) be a graph with directed edges. Then:

 $\blacktriangleright \sum_{v \in V} deg^{-}(v) = \sum_{v \in V} deg^{+}(v) = |\mathsf{E}|$

This is easy to see, because every new edge increases both the sum of in-degrees and the sum of out-degrees by one.



Definition: The complete graph on n vertices, denoted by K_n, is the simple graph that contains exactly one edge between each pair of distinct vertices.



▶ Definition: The cycle C_n , $n \ge 3$, consists of n vertices $v_1, v_2, ..., v_n$ and edges $\{v_1, v_2\}, \{v_2, v_3\}, ..., \{v_{n-1}, v_n\}, \{v_n, v_1\}.$



▶ Definition: We obtain the wheel W_n when we add an additional vertex to the cycle C_n , for $n \ge 3$, and connect this new vertex to each of the n vertices in C_n by adding new edges.



Definition: The n-cube, denoted by Q_n, is the graph that has vertices representing the 2ⁿ bit strings of length n. Two vertices are adjacent if and only if the bit strings that they represent differ in exactly one bit position.

Definition: A simple graph is called bipartite if its vertex set V can be partitioned into two disjoint nonempty sets V_1 and V_2 such that every edge in the graph connects a vertex in V_1 with a vertex in V_2 (so that no edge in G connects either two vertices in V_1 or two vertices in V_2).

►When this condition holds, we call the pair (V1, V2) a bipartition of the vertex set V of G.

► For example, consider a graph that represents each person in a mixed-doubles tennis tournament (i.e., teams consist of one female and one male player).

Players of the same team are connected by edges.

This graph is bipartite, because each edge connects a vertex in the subset of males with a vertex in the subset of females.

Example I: Is C₃ bipartite?

No, because there is no way to partition the vertices into two sets so that there are no edges with both endpoints in the same set.

Example II: Is C₆ bipartite?

Yes, because we can display C_6 like this:

Definition: The complete bipartite graph K_{m,n} is the graph that has its vertex set partitioned into two subsets of m and n vertices, respectively. Two vertices are connected if and only if they are in different subsets.

Operations on Graphs

▶ Definition: A subgraph of a graph G = (V, E) is a graph H = (W, F) where $W \subseteq V$ and $F \subseteq E$.

• A subgraph H of G is a proper subgraph of G if $H\neq G$.

Note: Of course, H is a valid graph, so we cannot remove any endpoints of remaining edges when creating H.

Example:

Operations on Graphs

Definition: The subgraph induced by a subset W of the vertex set V is the graph (W,F), where the edge set F contains an edge in E if and only if both endpoints of this edge are in W.

Operations on Graphs

• **Definition:** The **union** of two simple graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ is the simple graph with vertex set $V_1 \cup V_2$ and edge set $E_1 \cup E_2$.

The union of G_1 and G_2 is denoted by $G_1 \cup G_2$.

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