Introduction to Programming in Python

Assignment 5 (Atomic Nature of Matter) Discussion

Introduction

Goal: track the motion of particles undergoing Brownian motion, fit this data to Einstein's model, and estimate Avogadro's constant

Problem 1 (Particle Representation)

Define a data type called Blob in blob.py to represent a particle (aka blob). The data type must support the following API:

Blob()	constructs an empty blob b
b.add(x, y)	adds a pixel (x, y) to b
b.mass()	returns the mass of b, ie, the number of pixels in it
b.distanceTo(c)	returns the Euclidean distance between the center of mass of ${\tt b}$ and the center of mass of blob ${\tt c}$
str(b)	returns a string representation of b

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```

```
$ python3 blob.py
1 0 0 1 -1 0 0 -1
<ctrl-d>
a = 1 (0.0000, 0.0000)
b = 4 (0.0000, 0.0000)
dist(a, b) = 0.0
```

Problem 1 (Particle Representation)

Instance variables:

- x-coordinate of center of mass, _x (float)
- y-coordinate of center of mass, _y (float)
- Number of pixels, _pixels (int)

Blob()

- Initialize the instance variables appropriately

b.add(x, y)

- Use the idea of *running average*¹ to update the center of mass of blob b
- Increment the number of pixels in blob ${\tt b}$ by 1

b.mass()

- Return the number of pixels in the blob b

b.distanceTo(c)

- Return the Euclidean distance between the center of mass of blob b and the center of mass of blob c

¹If \bar{x}_{n-1} is the average value of n-1 points $x_1, x_2, \ldots, x_{n-1}$, then the average value \bar{x}_n of n points $x_1, x_2, \ldots, x_{n-1}, x_n$ is $\frac{\bar{x}_{n-1} \cdot (n-1) + x_n}{n}$.

Define a data type called BlobFinder in blob_finder.py that supports the following API. Use depth-first search to efficiently identify the blobs.

BlobFinder(pic, tau)	constructs a blob finder \mathtt{bf} to find blobs in the picture \mathtt{pic} using a luminance threshold \mathtt{tau}
<pre>bf.getBeads(pixels)</pre>	returns a list of all blobs with mass \geq pixels, ie, a list of beads

Problem 2 (Particle Identification)

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```
$ python3 blob_finder.py 25 180.0 data/run_1/frame00001.jpg
13 Beads:
29 (214.7241, 82.8276)
  (223.6111.116.6667)
36
42
  (260.2381, 234.8571)
   (266.0286, 315.7143)
35
  (286.5806, 355.4516)
37
  (299.0541.399.1351)
35
  (310.5143.214.6000)
15 Blobs:
29
  (214.7241.82.8276)
  (223.6111.116.6667)
36
  (254.0000, 223.0000)
  (260.2381.234.8571)
42
   (266.0286, 315.7143)
35
31
   (286.5806.355.4516)
   (299.0541.399.1351)
37
  (310.5143, 214.6000)
```

Problem 2 (Particle Identification)

Instance variable:

- Blobs identified by this blob finder, _blobs (list of Blob objects).

BlobFinder()

- Initialize blobs to an empty list.
- Create a 2D list of booleans called marked, having the same dimensions as pic.
- Enumerate the pixels of pic, and for each pixel (i, j):
 - create a Blob object called blob;
 - call _findBlob() with the appropriate arguments; and
 - add blob to blobs if it has a non-zero mass.

bf._findBlob()

- Base case: return if pixel (i, j) is out of bounds, or if it is marked, or if its luminance (use the luminance() method from Color for this) is less than tau.
- Mark the pixel (i, j).
- Add the pixel (i, j) to the blob blob.
- Recursively call _findBlob() on the N, E, W, and S pixels.

bf.getBeads(pixels)

- Return a list of blobs from blobs that have a mass $\geq \texttt{pixels}.$

Problem 3 (Particle Tracking)

Implement a program called bead_tracker.py that accepts p (int), tau (float), delta (float), and a sequence of JPEG filenames as command-line arguments; identifies the beads in each JPEG image using BlobFinder; and writes to standard output (one per line, formatted with 4 decimal places to the right of decimal point) the radial distance that each bead moves from one frame to the next (assuming it is no more than delta)

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<pre>\$ python3 bead_tracker.py data/run_1/frame00001.jpg 7.1833 4.7932 2.1693 5.5287 5.4292 4.3962</pre>	25 18	0.0 25.0	data/run_1/frame00000.jpg \					

Accept command-line arguments pixels (int), tau (float), and delta (float)

Construct a BlobFinder object for the frame sys.argv[4] and from it get a list of beads prevBeads that have at least pixels pixels

For each frame starting at sys.argv[5]:

- Construct a BlobFinder object and from it get a list of beads currBeads that have at least pixels pixels
- For each bead currBead in currBeads, find a bead prevBead from prevBeads that is no further than delta and is closest to currBead, and if such a bead is found, write its distance (using format string '%.4f\n') to currBead
- Write a newline character
- Set prevBeads to currBeads

Implement a program called avogadro.py that accepts the displacements (output of bead_tracker.py) from standard input; computes an estimate of Avogadro's constant using the formulae described above; and writes the value to standard output

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\$ python3 bead_tracker.py 25 180.0 25.0 data/run_1/* | python3 avogadro.py 6.633037e+23 Initialize ETA, RHO, T, and R to appropriate values

Calculate var as the sum of the squares of the n displacements (each converted from pixels to meters) read from standard input

Divide var by 2 * n

Estimate Boltzmann's constant as 6 * math.pi * var * ETA * RHO / T

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Estimate Avogadro's constant as R / k
```

Write to standard output the Avogadro constant in scientific notation (using the format string "%e")